

Analysis of Algorithms

Sorting

Andres Mendez-Vazquez

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Outline

1 Sorting problem

- Definition
- Classic Complexities

2 Heaps

- Introduction
- Heaps
- Finding Parents and Children
- Max-Heapify
- Complexity of Max-Heapify
- Build Max Heap: Using Max-Heapify
- Heap Sort

3 Applications of Heap Data Structure

- Main Applications of the Heap Data Structure
- Heap Sort: Exercises

4 Quicksort

- Introduction
- The Divide and Conquer Quicksort
- Complexity Analysis
- Unbalanced Partition
- It is Necessary to Model the Worst Case!!!
- Randomized Quicksort
- Expected Running Time

5 Lower Bounds of Sorting

- Lower Bounds of Sorting
- Exercises



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Input

A sequence of n numbers $\langle a_1, a_2, \dots, a_n \rangle$.

Output

A permutation (reordering) $\langle a'_1, a'_2, \dots, a'_n \rangle$ such that $a'_1 \leq a'_2 \leq \dots \leq a'_n$.



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Some Sorting Algorithms

Table of Sorting Algorithms

Algorithm	Worst-case running time	Expected running time
Insertion sort	$\Theta(n^2)$	$\Theta(n^2)$
Merge sort	$\Theta(n \log n)$	$\Theta(n \log n)$
Heapsort	$\Theta(n \log n)$	-
Quicksort	$\Theta(n^2)$	$\Theta(n \log n)$ (expected)
Countingsort	$\Theta(k + n)$	$\Theta(k + n)$
Radix sort	$\Theta(d(k + n))$	$\Theta(d(k + n))$
Bucket sort	$\Theta(n^2)$	$\Theta(n)$ (average-case)



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Imagine 1964

The System/360 family was introduced by IBM

The slowest System/360, the Model 30, could perform up to 34,500 instructions per second, with memory from 8 to 64 KB.

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Additionally, POINTERS were invented this year barely.

Therefore... back to first principles my dear Clarice...



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Yepi

Yes... my dear Clarice...



Then, if you put all together

We have a memory structure like



Let us to think about it

How? We can assume a series of constraints...



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Constraints

We want a system that allows for priorities such that

- We do not want to scan the entire memory for that.
- We want to avoid doing a lot of shifting in the main memory.

Requirements

We want that allows the following ADT operations:

- Insertion
- Deletion
- Search

in a Time LESS than

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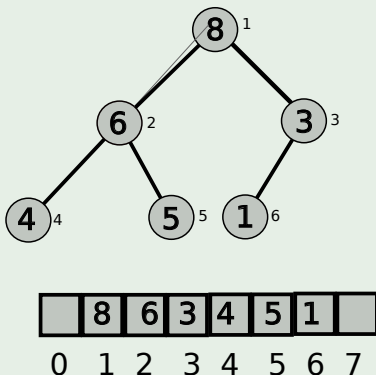
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Definitions

Definition

A heap is an array object that can be viewed as a nearly complete binary tree.



Basic Attributes

Given an array A , we have that $length[A]$

It is the size of the storing array.

$heap-size[A]$

Tell us how many elements in the heap are stored in the array.

Thus, we have

$$0 \leq heap-size[A] \leq length[A] \quad (1)$$



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Heap Sort: Calculations given a Node i in the heap

Parent(i) - Parent Node

$$\text{Parent}(i) = \left\lfloor \frac{i}{2} \right\rfloor$$

Left Node Child: *Left*(i)

$$\text{Left}(i) = 2i$$

Right Node Child: *Right*(i)

$$\text{Right}(i) = 2i + 1$$



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Max/Min Heap Properties

Given that

$A[i]$ returns the value of the key, we have that

Max Heap property

$$A[\text{Parent}(i)] \geq A[i]$$

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What we want!!!

A function to keep the property of max or min heap

After all, remembering Kolmogorov, we are acting in a part of the array trying to keep certain properties

- Which ONE?

Remember



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- Which ONE?

Remember

Single nodes are always min heaps or max heaps



Heap Sort: Max-Heapify

Algorithm (preserving the heap property) when somebody violates the max/min property

Max-Heapify(A, i)

- 1 $l = \text{Left}(i)$
- 2 $r = \text{Right}(i)$
- 3 if $l \leq \text{heap-size}[A]$ and $A[l] > A[i]$
- 4 $\text{largest} = l$
- 5 else $\text{largest} = i$
- 6 if $r \leq \text{heap-size}[A]$ and $A[r] > A[\text{largest}]$
- 7 $\text{largest} = r$
- 8 if $\text{largest} \neq i$
- 9 exchange $A[i]$ with $A[\text{largest}]$
- 10 Max-Heapify($A, \text{largest}$)

Figure: A trickle down algorithm

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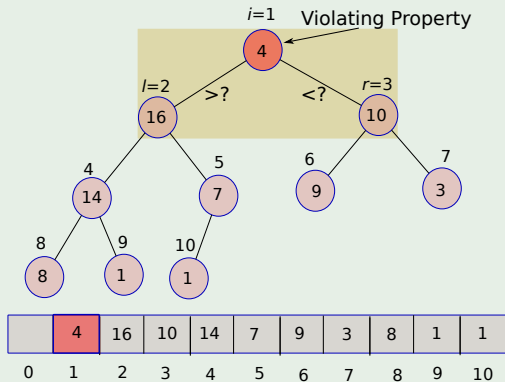
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Example keeping the heap property starting at $i = 1$

Here, you could imagine that somebody inserted a node at $i = 1$

3. If $l \leq \text{heap-size}[A]$ and $A[l] > A[i]$
4. $\text{largest} = l$
5. else $\text{largest} = i$
6. If $r \leq \text{heap-size}[A]$ and $A[r] > A[\text{largest}]$
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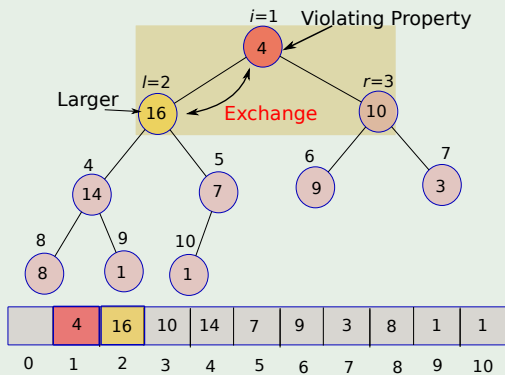


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One of the children is chosen to be exchanged

8. if $largest \neq i$

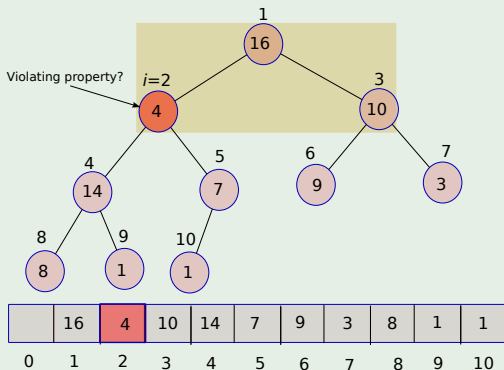
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Example: Now $i = largest$

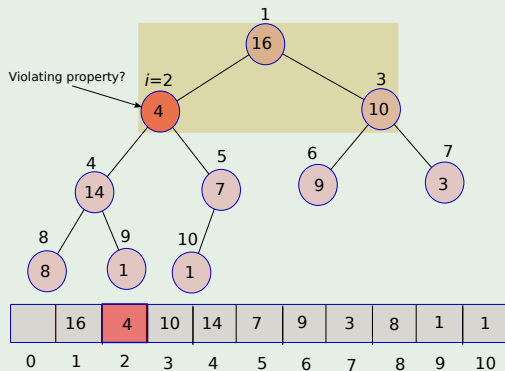
Make the exchange and call the **Max-Heapify**

10. **Max-Heapify**($A, largest$)



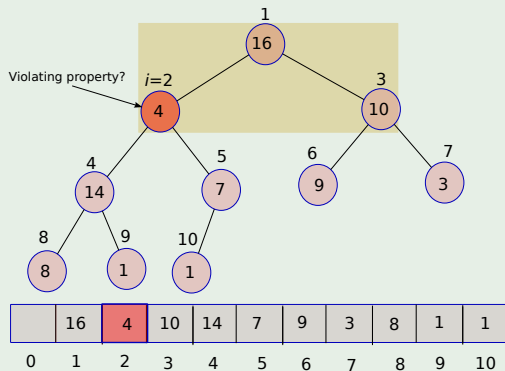
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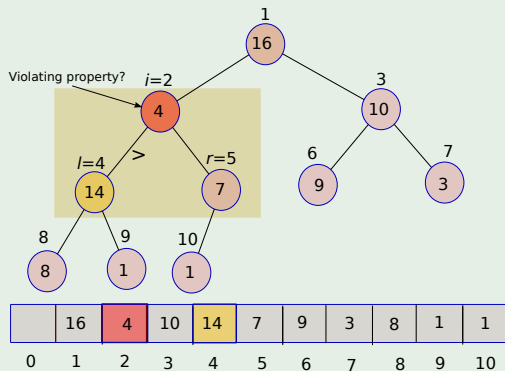
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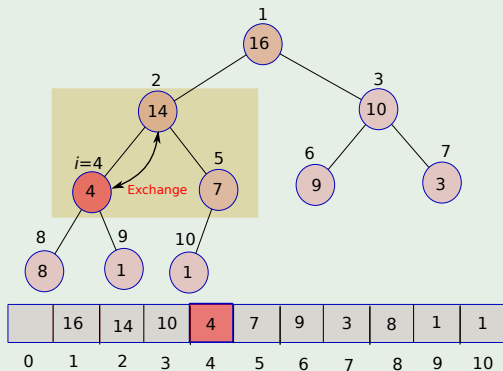
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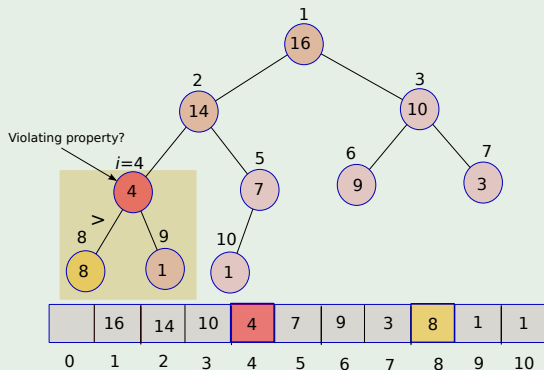
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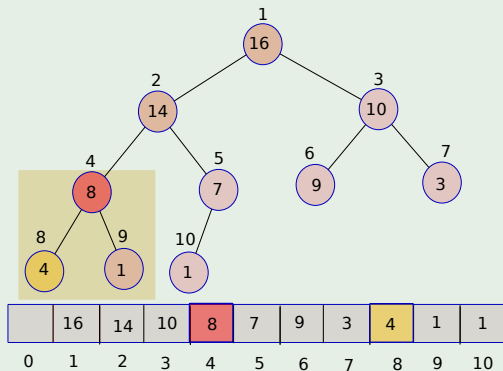
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For this

It is possible to prove that the upper bound on the size of each children's subtrees is $\frac{2n}{3}$ starting at the root (First Recursive Call!!!).

Thus

In addition, we use the idea of height from the root node ($h = 0$) to leaves ($h = \log n - 1$).



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Then

We have that by using the nearly complete structure

- 1 First for $n = 1$, we have that the size of children's subtrees is $0 < \frac{2}{3}$.
- 2 For $n = 2$, we have that the size of children's subtrees is at most $1 < \frac{4}{3}$.
- 3 For $n = 3$, we have that the size of children's subtrees is at most $1 < \frac{6}{3} = 2$.
- 4 For $n = 4$, we have that the size of children's subtrees is at most $2 < \frac{8}{3}$.
- 5 etc...



Then

We have that by using the nearly complete structure

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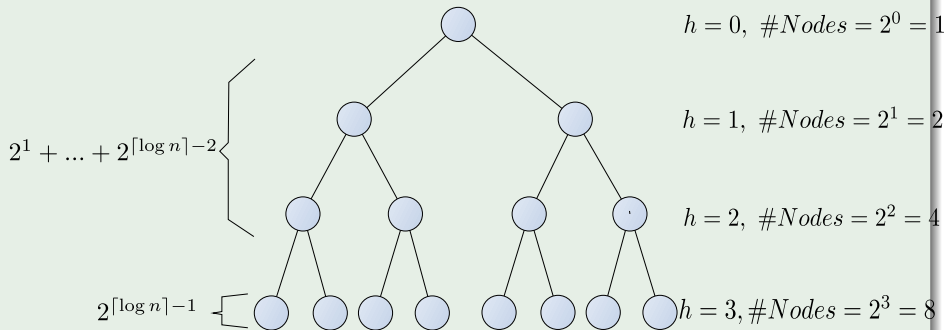
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Do you notice the following?

Imagine the following case

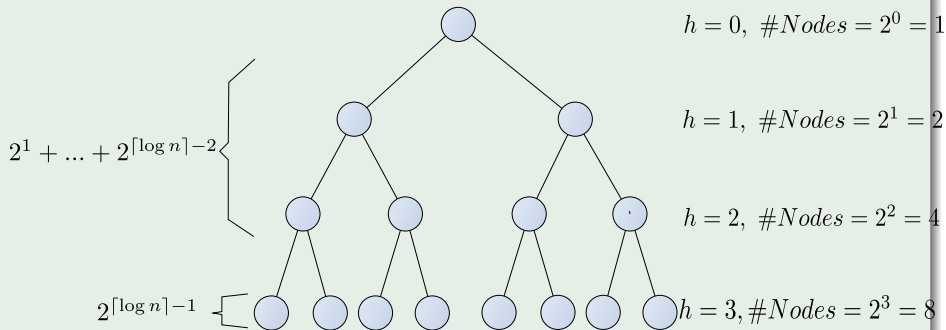


The maximum number of nodes in both children assuming a full tree with n nodes

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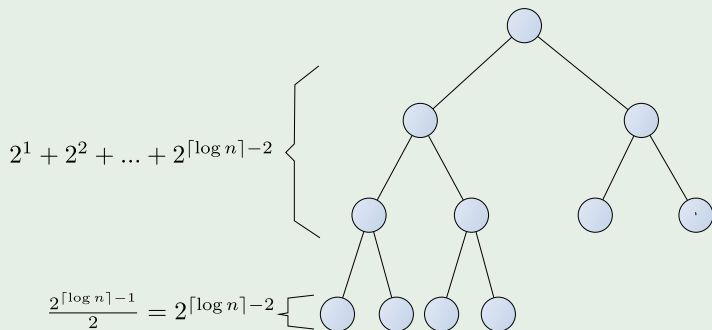


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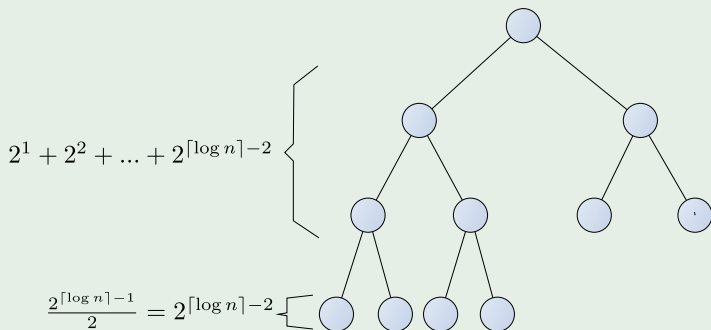


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The total number of elements in a child's subtree

The total number of nodes in a CHILD is bounded

$$\begin{aligned} \frac{2^1 + 2^2 + \dots + 2^{\lceil \log n \rceil - 2}}{2} + 2^{\lceil \log n \rceil - 2} &= 1 + 2^2 + \dots + 2^{\lceil \log n \rceil - 3} + 2^{\lceil \log n \rceil - 2} \\ &= \frac{1 - 2^{\lceil \log n \rceil - 2}}{1 - 2} + 2^{\lceil \log n \rceil - 2} \\ &= 2^{\lceil \log n \rceil - 2} - 1 + 2^{\lceil \log n \rceil - 2} \\ &= 2 \times 2^{\lceil \log n \rceil - 2} - 1 \\ &= 2^{\lceil \log n \rceil - 1} - \frac{2}{3} - \frac{1}{3} \\ &< 2^{\lceil \log n \rceil - 1} - \frac{2}{3} \end{aligned}$$



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The total number of elements in a child's subtree

Notice the following

$$2^{\lceil \log n \rceil} < \frac{4}{3} \left[2^{\log n} \right] \quad (4)$$

- When $n = 2^p - 1$
- For the case that that $n \leq 2^p - 1$ we can use the fact that $\lceil \log n \rceil = p$ for some power of 2.



Induction to prove the previous statement

Step $n = 1$

$$2^{\lceil \log 1 \rceil} = 2^0 = 1 < \frac{4}{3} \times 2^{\log 1} \quad (5)$$

Assume is true for n

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1 Sorting problem

- Definition
- Classic Complexities

2 Heaps

- Introduction
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- Finding Parents and Children
- Max-Heapify
- **Complexity of Max-Heapify**
- Build Max Heap: Using Max-Heapify
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Complexity of Max-Heapify

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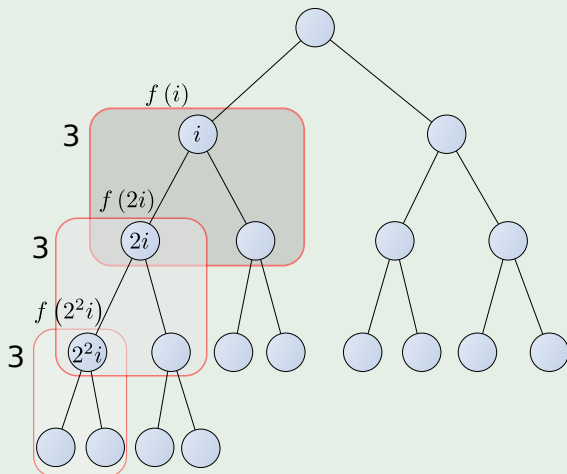
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Complexity of Max-Heapify

The Recursion Idea



Complexity of Max-Heapify

Thus

$$\sum_{i=1}^{\frac{\log_2 n - 1}{2} - 1} 3 = \frac{3^{\frac{\log_2 n}{2} - 1} - 1}{3 - 1} - 3$$

$$= \frac{\left(3^{\frac{1}{2}}\right)^{\log_2 n}}{2} - 3$$

$$= \frac{n^{\log_2\left(3^{\frac{1}{2}}\right)}}{2} - 3$$

$$\leq \frac{n^{0.8}}{2}$$

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Complexity of Max-Heapify

Thus, if we assume that T is an increasing monotone function

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Heap Sort: Using Max-Heapify

Algorithm Build-Max-Heap

Build-Max-Heap(A)

- 1 $heap - size[A] = length[A]$
- 2 for $i = \lfloor length[A]/2 \rfloor$ downto 1
- 3 **Max-Heapify**(A, i)

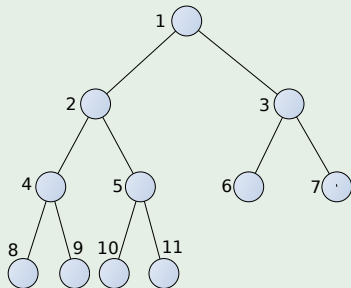
Figure: Building a Heap



Question?

Why from $\lfloor \text{length}[A]/2 \rfloor$?

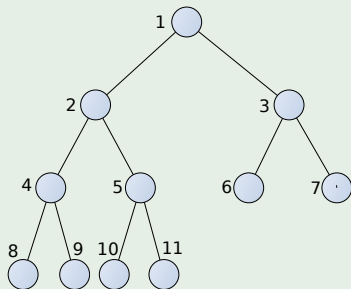
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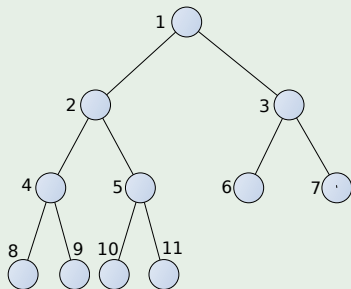
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- This can be proved by induction on n !!!
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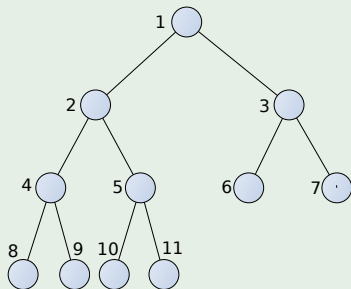
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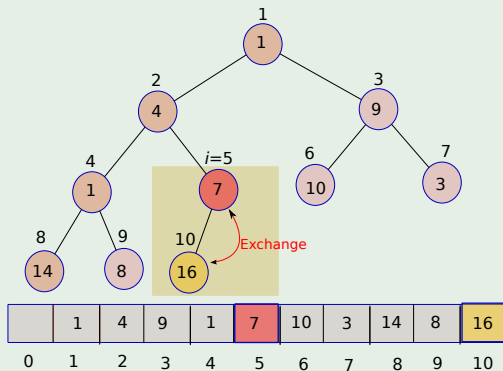
What about the loop invariance?

Look at the Board!!!



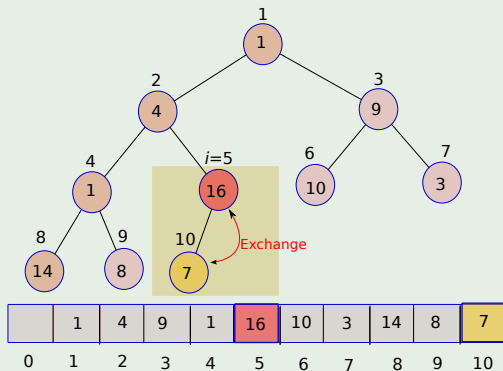
Build Max Heap: Using Max-Heapify

Example



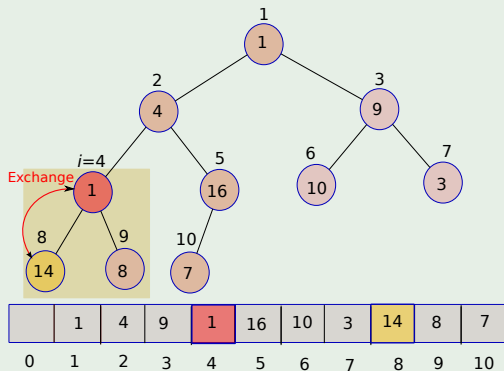
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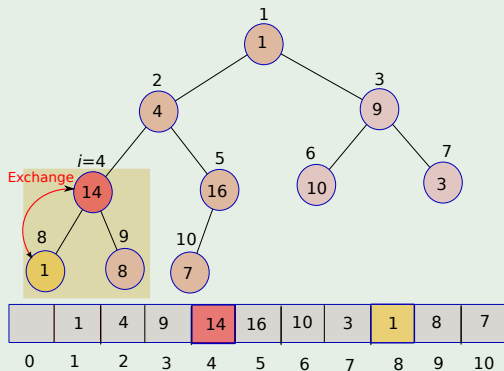
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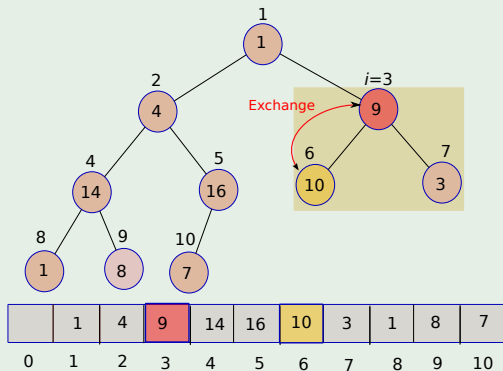
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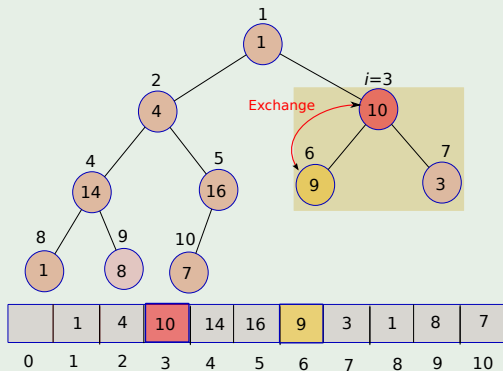
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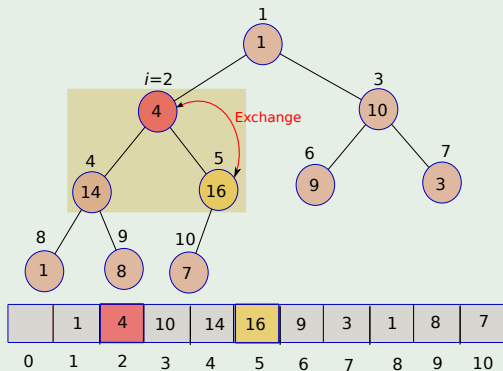
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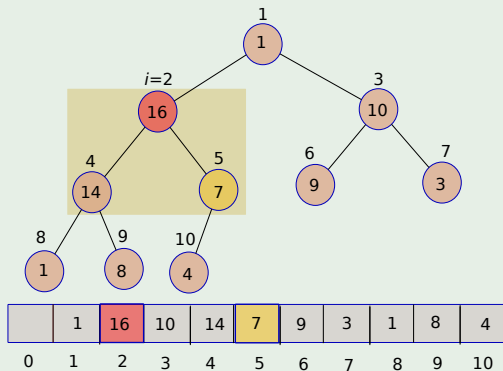
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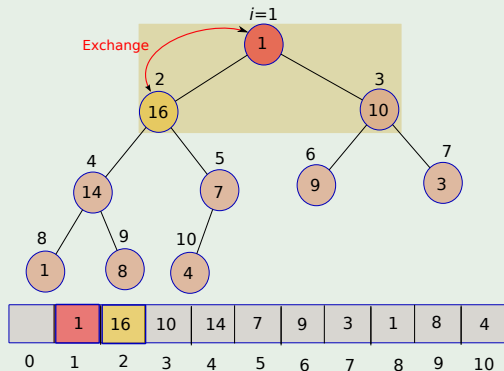
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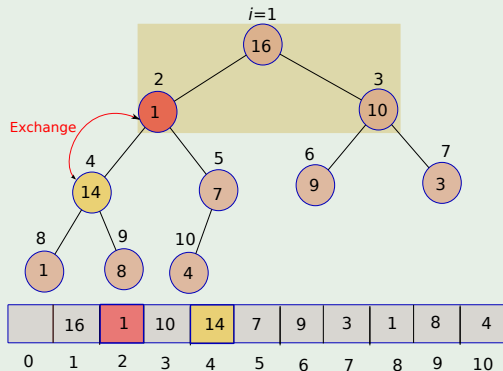
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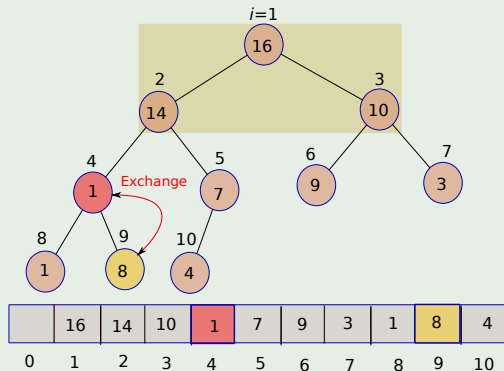
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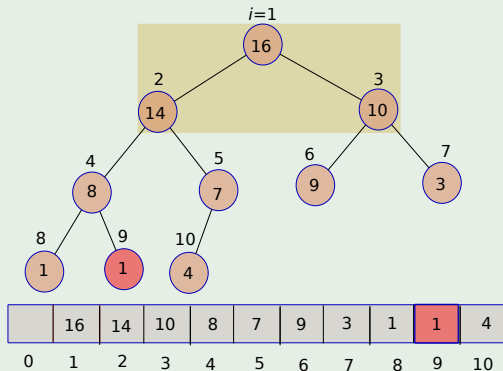
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Height h of the Heap for Complexity of Build-Max-Heap

We can use the height of a tree to derive a tight bound

- The height h is the number of edges on the longest simple downward path from the node to a leaf.
- You have at most $\left\lfloor \frac{n}{2^{h+1}} \right\rfloor$ nodes at height h , where n is the total number of nodes.



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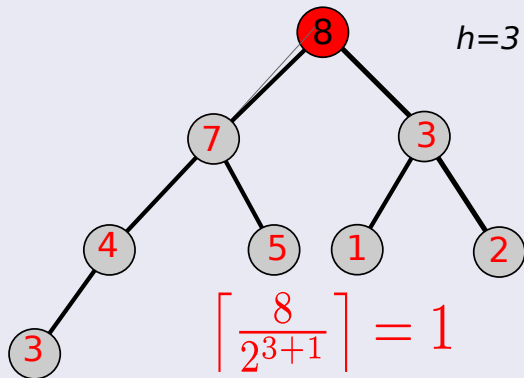
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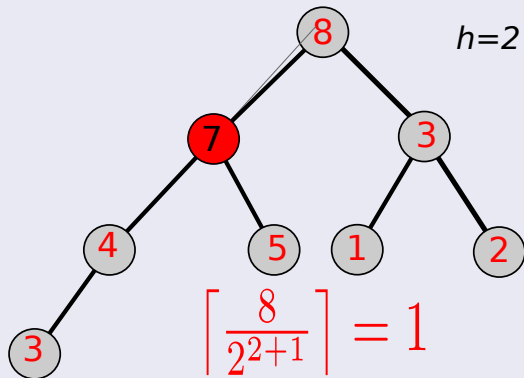
$h = 1$



univestav

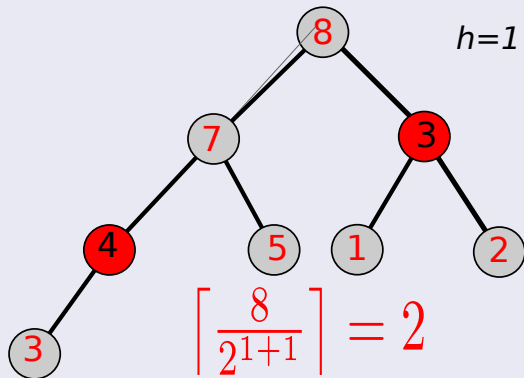
Furthermore

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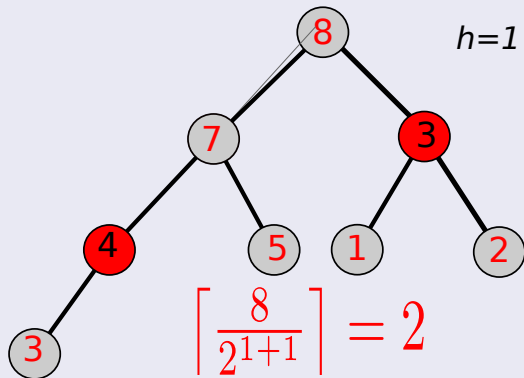
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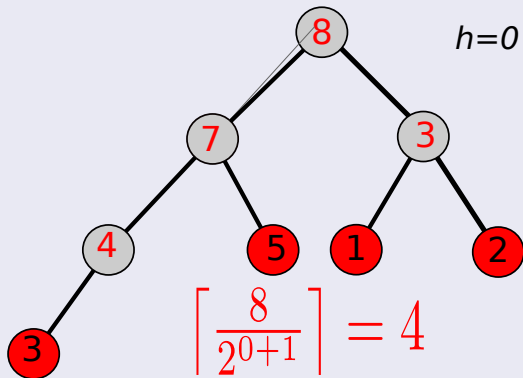
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Furthermore

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Cost of Building the Build-Max-Heap

Possible cost

$$O(n \log_2 n)$$

(9)



Cost of Building the Build-Max-Heap

We have that you have

- The number of nodes **explored horizontally** by the “for” loop can be bounded by

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Heap Sort: Using Max-Heapify

Heapsort Algorithm

Heapsort(A)

- Build-Max-Heap(A)
- for $i = \text{length}[A]$ downto 2
- exchange $A[1]$ with $A[i]$
- $\text{heap-size}[A] = \text{heap-size}[A] - 1$
- Max-Heapify($A, 1$)

Figure: Heapsort



Heap Sort: Using Max-Heapify

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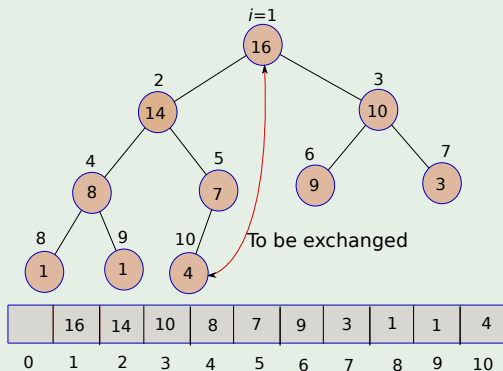
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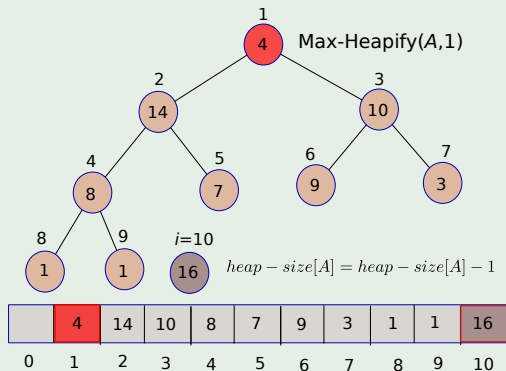
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Example: Heapsort in action! By Moving the top element to the bottom position!!!



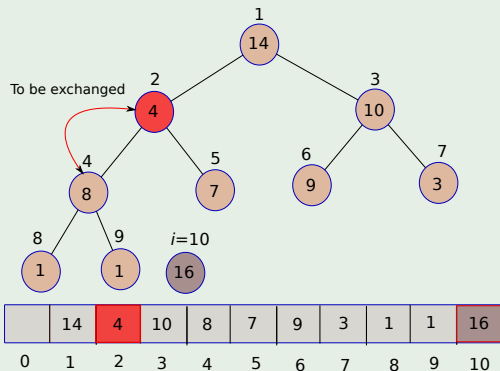
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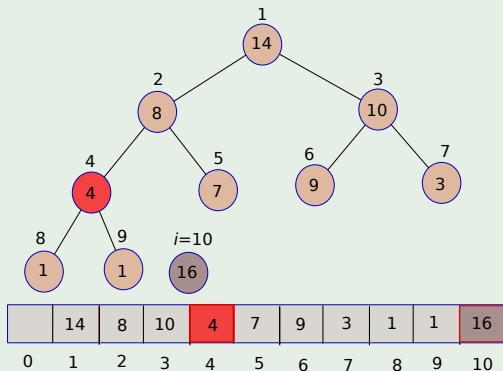
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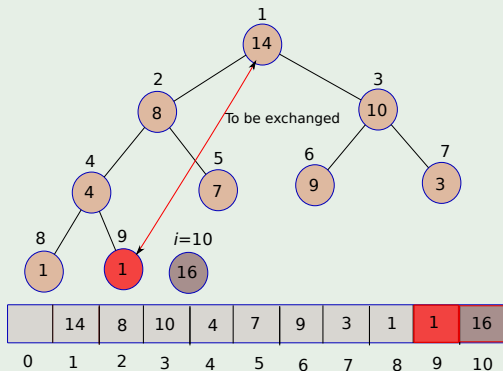
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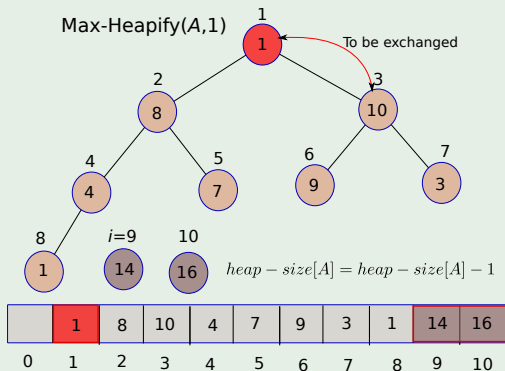
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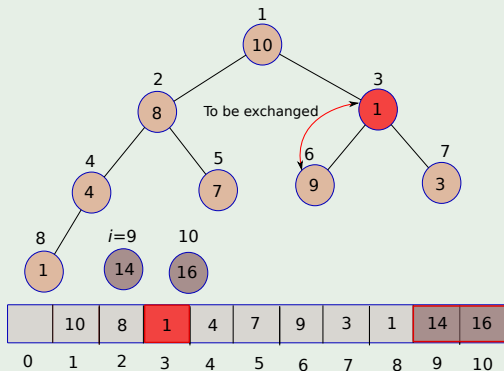
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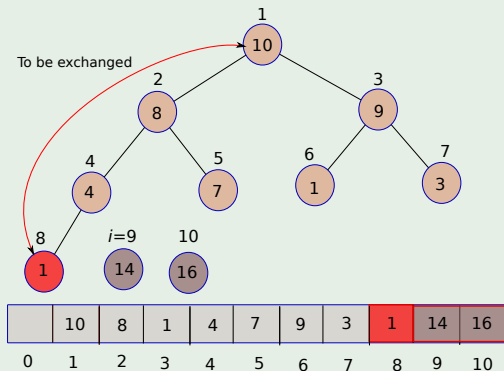
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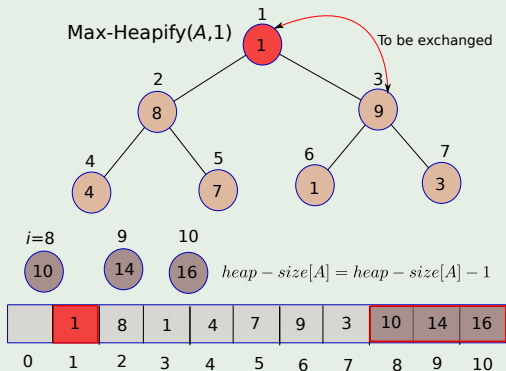
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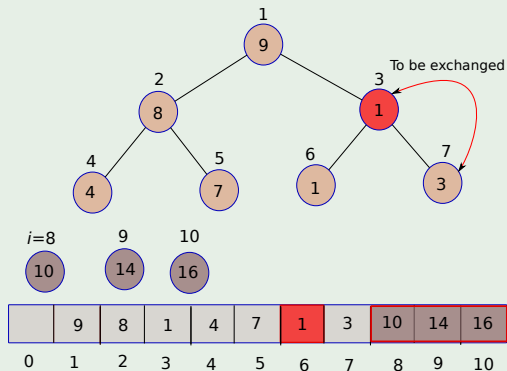
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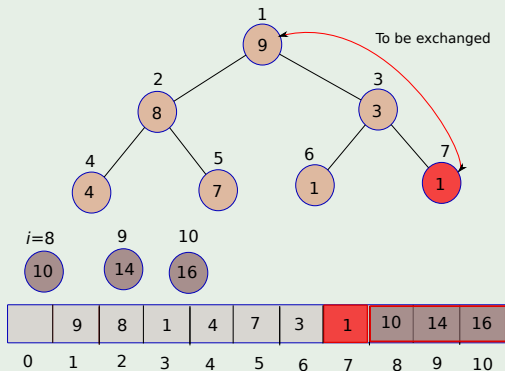
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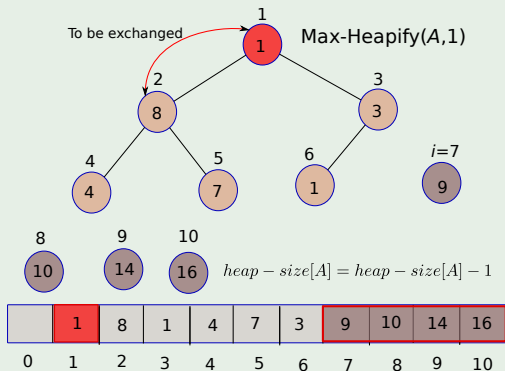
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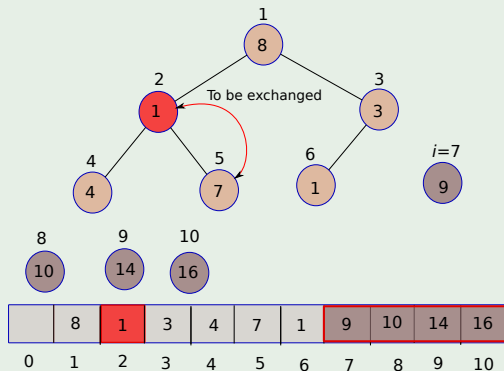
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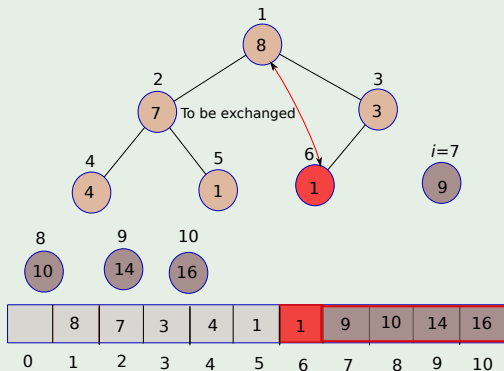
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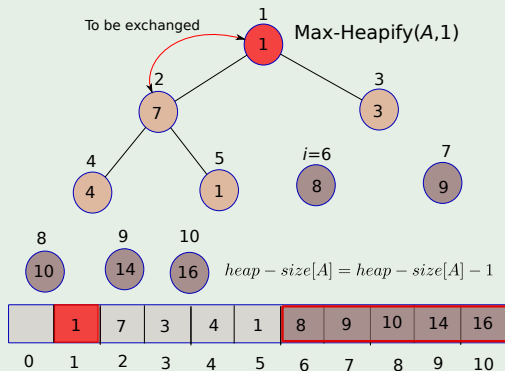
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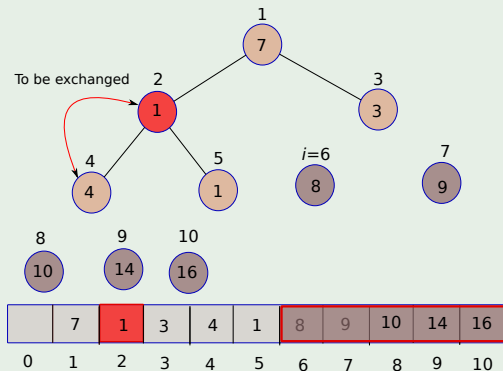
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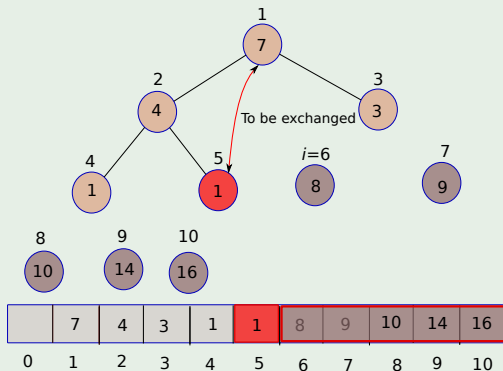
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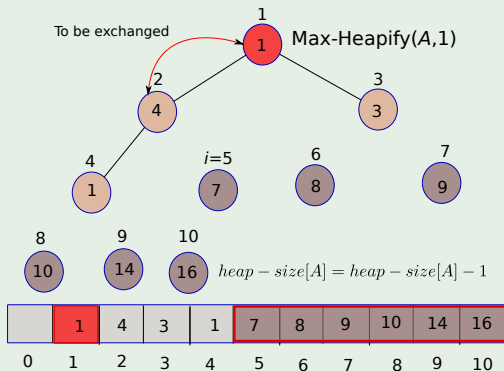
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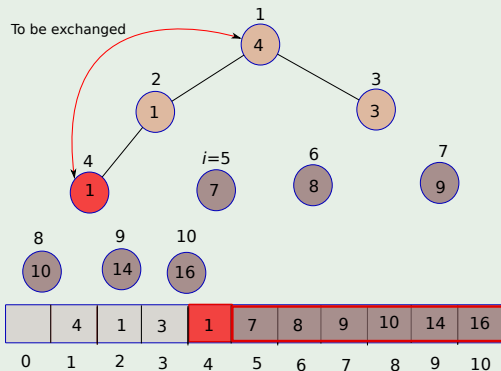
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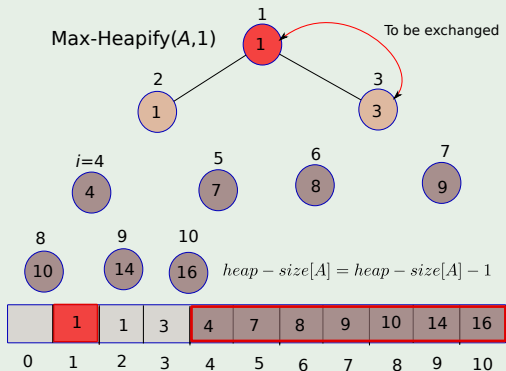
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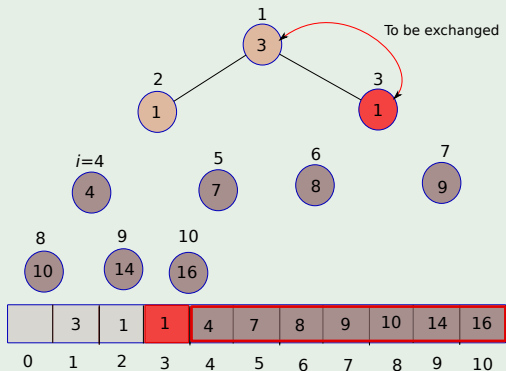
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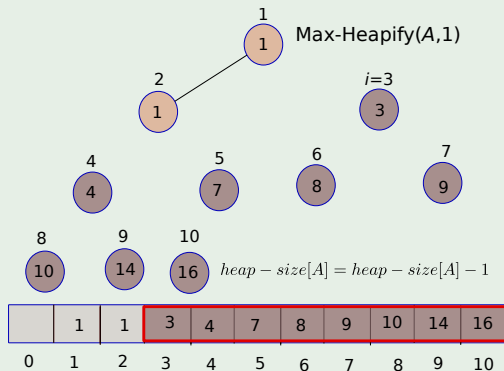
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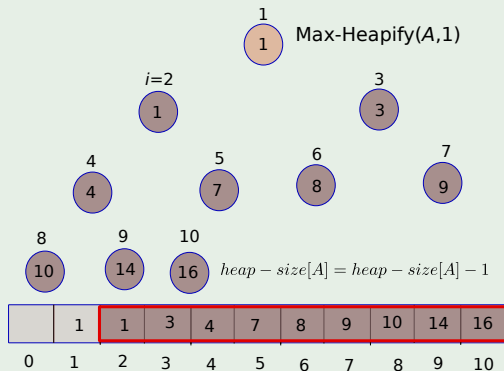
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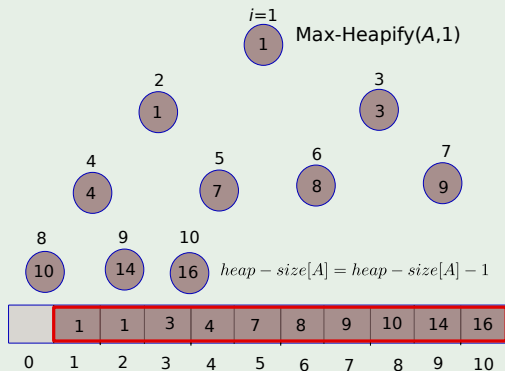
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Cost

$O(n \log n)$



onyxstep

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Applications of Heap Data Structure

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This has direct applications

- 1 Bandwidth management:
 - 1 Many modern protocols for Local Area Networks include the concept of Priority Queues at the Media Access Control (MAC).
- 2 Discrete Event Simulations
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 - 1 It computes a dynamically changing triangulation of a terrain using two priority queues.

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Applications of Heap Data Structure

Heap Sort of Arrays

Clearly, if the list of numbers is stored in an array!!!



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- **Heap Sort: Exercises**

4 Quicksort

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5 Lower Bounds of Sorting

- Lower Bounds of Sorting
- Exercises



Heap Sort: Exercices

From Cormen's book

- 6.1-1
- 6.1-4
- 6.1-7
- 6.2-5
- 6.2-6
- 6.3-3
- 6.4-2
- 6.4-3
- 6.4-4



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Who invented Quicksort?

Imagine this

The Quicksort algorithm was developed in 1960 by Tony Hoare (He has a postgraduate certificate in Statistics) while in the Soviet Union, as a visiting student at Moscow State University.

Why?

At that time, Hoare worked in a project on machine translation for the National Physical Laboratory.

How?

He developed the algorithm in order to sort the words to be translated.



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Imagine the following...

First Attempt

We want an algorithm that can sort by using the Divide and Conquer method

Now, we have the following constraint:

We need to use the same array to do the sorting!!! Sorting in place!!!

What if we use the following strategy:

Given a number in the array!!!

- Move some elements to the left of the number!!!
- Move some other elements to the right of the number!!!

Imagine the following...

First Attempt

We want an algorithm that can sort by using the Divide and Conquer method

Now, we have the following constraint

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Given a number in the array!!!

- Move some elements to the left of the number!!!
- Move some other elements to the right of the number!!!

Something like

We have...

9	8	2	4	5	10	6	3	7
---	---	---	---	---	----	---	---	---



2	4	3	5	9	8	10	6	7
---	---	---	---	---	---	----	---	---

Now, What?

- Any Ideas?



Something like

We have...

9	8	2	4	5	10	6	3	7
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Now What?

- Any Ideas?
- What about our old friend? Recursion!!!



The Divide and Conquer Quicksort

Divide Process

- 1 Compute the index q as part of this partitioning procedure.
- 2 Partition (rearrange) the array $A[p, \dots, r]$ into two (possibly empty) sub-arrays $A[p, \dots, q - 1]$ and $A[q + 1, \dots, r]$
 - 3 each element of $A[p, \dots, q - 1]$ is less than or equal to $A[q]$.
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The Divide and Conquer Quicksort

Conquer

Sort the two sub-arrays $A[p, \dots, q - 1]$ and $A[q + 1, \dots, r]$ by recursive calls to quicksort.

Combine

Since the sub-arrays are sorted in place, no work is needed to combine them: the entire array $A[p, \dots, r]$ is now sorted.



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Quicksort Algorithm

Quicksort Algorithm

Quicksort(A, p, r)

- 1 if $p < r$
 - 2 $q = \text{Partition}(A, p, r)$
 - 3 **Quicksort**($A, p, q - 1$)
 - 4 **Quicksort**($A, q + 1, r$)



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Partition Algorithm

Quicksort Partition

Partition(A, p, r)

- 1 $x = A[r]$
- 2 $i = p - 1$
- 3 for $j = p$ to $r - 1$
- 4 if $A[j] \leq x$
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- 8 return $i + 1$



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Quicksort: What is the Invariance?

Loop Invariance

- 1 If $p \leq k \leq i$, then $A[k] \leq x$.
- If $i+1 \leq k \leq j-1$, then $A[k] > x$.
- If $k = r$, then $A[k] = x$.
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Proof of the Loop Invariance

Look at the Board.



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Complexity Analysis

Best-case Analysis

- Partition returns two arrays size $\frac{n}{2}$ and $\frac{n}{2} - 1$.
- Then, we have the recurrence $T(n) = 2T(\frac{n}{2}) + \Theta(n)$.

What about the Worst-Case?

- Partition returns two arrays, one of size 0 and one of size $n - 1$.
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$$T(n) = T(n - 1) + \Theta(n) = O(n^2). \quad (12)$$



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What about a No So Unbalanced Partition?

What are you talking about?

$$T(n) = T\left(\frac{n}{10}\right) + T\left(\frac{9n}{10}\right) + \Theta(n) \quad (13)$$

What can happen when...

The pivot split the array in two sub-array...

x_1	pivot	x_2	x_3	x_4	x_5	x_6	x_7	x_8	x_9
-------	-------	-------	-------	-------	-------	-------	-------	-------	-------

Even when this happen

Using the tree method!!! We notice something weird!!!



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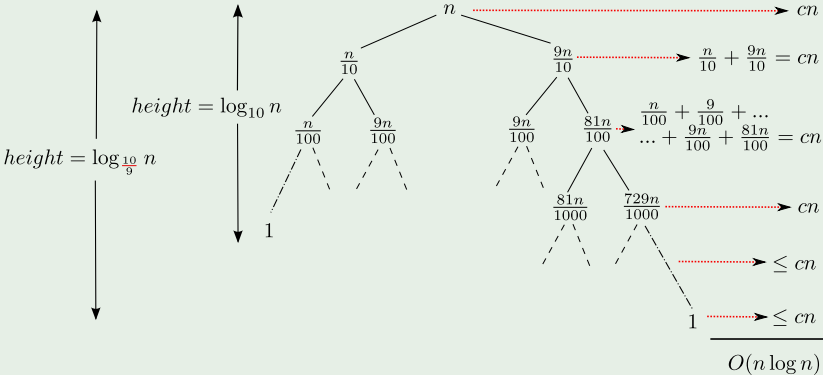
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Unbalanced Partition Tree Method Analysis

Unbalanced partitioning returns a $O(n \log n)$

After certain level, the total steps are \leq than $cn!!!$



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Worst Case Complexity Analysis

We do not know which pivot gets the worst case

Thus, Why do not ask the recursion each possible pivot?

We can get the worst case asking

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Remember!!!

After all, we can split the sub-arrays in any way we want!!!

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$$T(n) = \max_{0 \leq q \leq n-1} (T(q) + T(n - q - 1)) + \Theta(n) \quad (16)$$

By substitution, we can prove

Complexity $O(n^2)$.

This can be proved as follows

BLACKBOARD!



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Remember?

The use of uniform distribution

To get the average behavior!!!

In many cases

It is better than the worst case scenario....

Thus

We can introduce randomization in the Quicksort.



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To get the average behavior!!!

In many cases

It is better than the worst case scenario....

Thus

We can introduce randomization in the Quicksort.



Randomized Quicksort

RANDOMIZED-QUICKSORT(A, p, r)

Randomized-Quicksort(A, p, r)

- 1 if $p < r$
 - 2 $q = \text{Randomized-Partition}(A, p, r)$
 - 3 Randomized-Quicksort($A, p, q - 1$)
 - 4 Randomized-Quicksort($A, q + 1, r$)



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RANDOMIZED-PARTITION(A, p, r)

Randomized-Partition(A, p, r)

- 1 $i = \text{Random}(p, r)$
- 2 exchange $A[r]$ with $A[i]$
- 3 **return** Partition(A, p, r)

Outline

1 Sorting problem

- Definition
- Classic Complexities

2 Heaps

- Introduction
- Heaps
- Finding Parents and Children
- Max-Heapify
- Complexity of Max-Heapify
- Build Max Heap: Using Max-Heapify
- Heap Sort

3 Applications of Heap Data Structure

- Main Applications of the Heap Data Structure
- Heap Sort: Exercises

4 Quicksort

- Introduction
- The Divide and Conquer Quicksort
- Complexity Analysis
- Unbalanced Partition
- It is Necessary to Model the Worst Case!!!
- Randomized Quicksort
- **Expected Running Time**

5 Lower Bounds of Sorting

- Lower Bounds of Sorting
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Expected Running Time of Randomized Quicksort

Expected running time

The expected running time for the Randomized Quicksort algorithm arises from the following lemma.

Lemma 7.1 (Gormen's book)

- Let X be the number of comparisons performed in line 4 of PARTITION algorithm over the entire execution of QUICKSORT on an n -element array.
- Then, the running time of QUICKSORT is $O(n + X)$.

Now, the proof of the expected running time.

BLACKBOARD!



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Therefore

It is possible to conclude that

The Average Time Complexity of the Quicksort is $O(n \log n)$



Sorting in Special Environments

Example: Using Massive Parallel Stream Processors.

Multi-Objective Optimization

Yes!!! Numerical Analysis using the Quick Sort!!!

Real-Time Visualization of Large Time-Varying Molecules

Use the distance of the atoms to the viewers - the Painters Algorithms!!!



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Basic Concepts

Mergesort and Heapsort

- They are algorithms that sort in $O(n \log n)$.
- It is more we can give a sequence such that $\Omega(n \log n)$.



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Any comparison sort algorithm requires $\Omega(n \log n)$ comparisons in the worst case.

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Exercises

Cormen's Chapter 7

- 7.1-4
- 7.2-3
- 7.2-5
- 7.4-1

