

# Artificial Intelligence

## Causality in Bayesian Networks

Andres Mendez-Vazquez

February 11, 2020

# Outline

- 1 Causality
  - Example
  - Definition of Causal Structure
  - Causal Networks
    - Causal Chains
    - Common Causes
    - Common Effect
- 2 Analyze the Graph
  - Going Further
  - D-Separation
    - Paths
    - Blocking
    - Definition of D-Separation
- 3 Algorithms to Find D-Separations
  - Introduction
    - Example of Reachability
  - Reachability Algorithm
  - Analysis
  - D-Separation Finding Algorithm
    - Analysis
    - Example of D-Separation
  - Application
- 4 Final Remarks
  - Encoding Causality



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# Causality

## What do we naturally?

A way of structuring a situation for reasoning under uncertainty is to construct a graph representing causal relations between events.

### Example of events with possible outputs

- Fuel? {Yes, No}
- Clean Spark Plugs? {full, 1/2, empty}
- Start? {Yes, No}



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## We know

We know that the state of **Fuel?** and the state of **Clean Spark Plugs?** have a causal impact on the state of **Start?**.

This we have something like

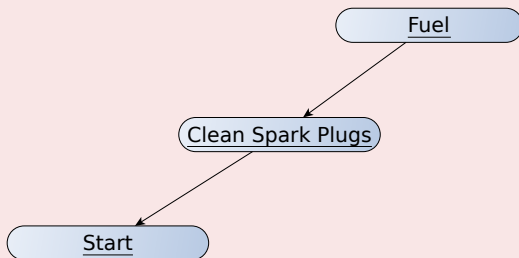


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We know that the state of **Fuel?** and the state of **Clean Spark Plugs?** have a causal impact on the state of **Start?**.

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# Causal Structure - Judea Pearl (1988)

## Definition

A causal structure of a set of variables  $V$  is a directed acyclic graph (DAG) in which each node corresponds to a distinct element of  $V$ , and each edge represents direct functional relationship among the corresponding variables.

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Causal Structure  $\cong$  A precise specification of how each variable is influenced by its parents in the DAG.



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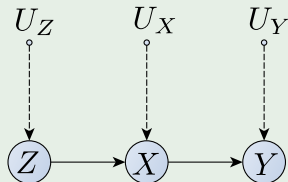
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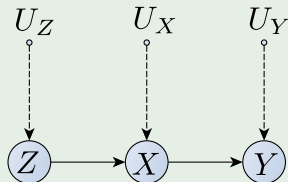
From the point of view of Statistics





# Example

## From the point of view of Statistics



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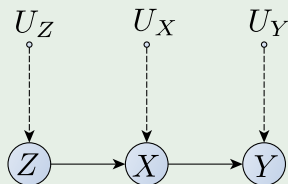
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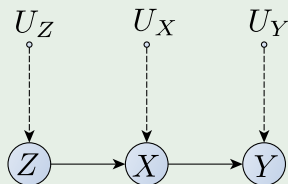
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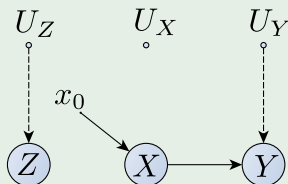
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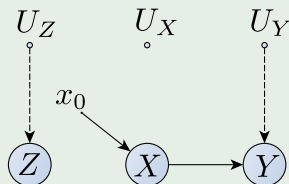
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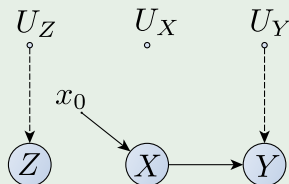
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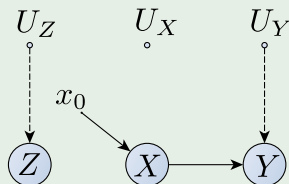
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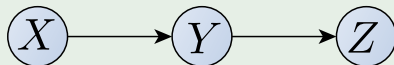
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# Causal Chains

This configuration is a “causal chain”



$X$  : Low Pressure

$Y$  : Rain

$Z$  : Traffic

What about the Joint Distribution

We have by the Chain Rule

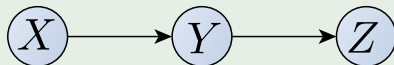
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Given no information about  $Y$

Information can propagate from  $X$  to  $Z$ .

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The natural question is What does happen if  $Y = y$  for some value  $y$ ?



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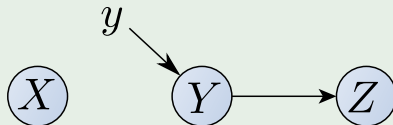
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# Using Our Probabilities

Then  $Z$  is independent of  $X$  given a  $Y = y$

And making the assumption that once an event happens

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**YES!!!**

Evidence along the chain “blocks” the influence.



Thus

### Something Notable

Knowing that  $X$  has occurred does not make any difference to our beliefs about  $Z$  if we already know that  $Y$  has occurred.

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The Joint Probability is equal to

$$P(X, Y = y, Z) = P(X) P(Y = y|X) P(Z|Y = y) \quad (4)$$



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Is  $X$  independent of  $Z$  given  $Y = y$ ?

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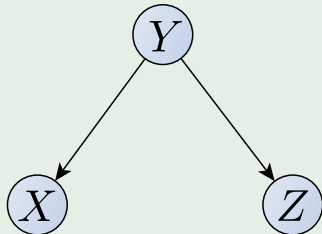
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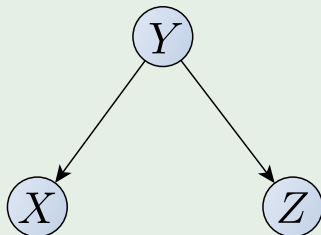
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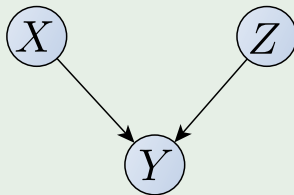
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Last configuration: two causes of one effect (v-structures)

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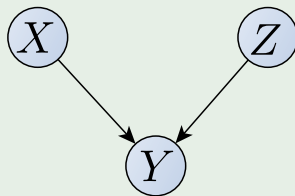
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### Q18

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## Definition 2.1

- Let  $G = (V, E)$  be a DAG, where  $V$  is a set of random variables. We say that, based on the Markov condition,  $G$  entails conditional independence:

▶  $I_P(A, B|C)$  for  $A, B, C \subseteq V$  if  $I_P(A, B|C)$  holds for every  $P \in P_G$ , where  $P_G$  is the set of all probability distributions  $P$  such that  $(G, P)$  satisfies the Markov condition.



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We also say the Markov condition entails the conditional independence for  $G$  and that the conditional independence is in  $G$ .



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## Question

In a given Bayesian Network, Are two variables independent (Given evidence)?

## Solution

Analyze Graph Deeply!!!





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# Examples of Entailed Conditional independence

## Example

G: Graduate Program Quality.

F: First Job Quality.

B: Number of Publications.

C: Number of Citations.

F is given some evidence!!!



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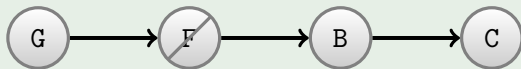
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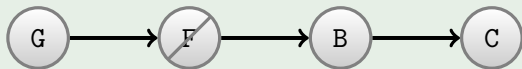
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If the graph satisfies the Markov Condition



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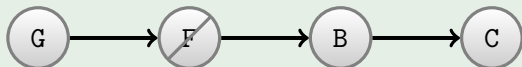
Thus

$$\begin{aligned} P(C|G, F = f) &= \sum_b P(C|B = b, G, F = f) P(B = b|G, F = f) \\ &= \sum_b P(C|B = b, F = f) P(B = b|F = f) \\ &= P(C|F = f) \end{aligned}$$



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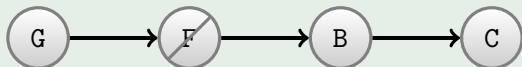
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Finally

We have

$$I_p(C, G|F) \quad (7)$$

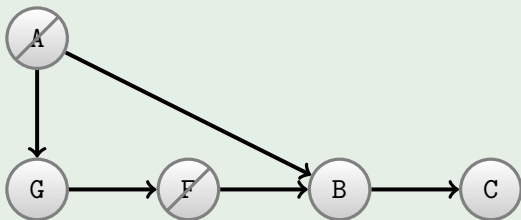


Cinvestav

# D-Separation $\approx$ Conditional independence

F and G are given as evidence

Example C and G are d-separated by A, F in the DAG in



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# Basic Definitions

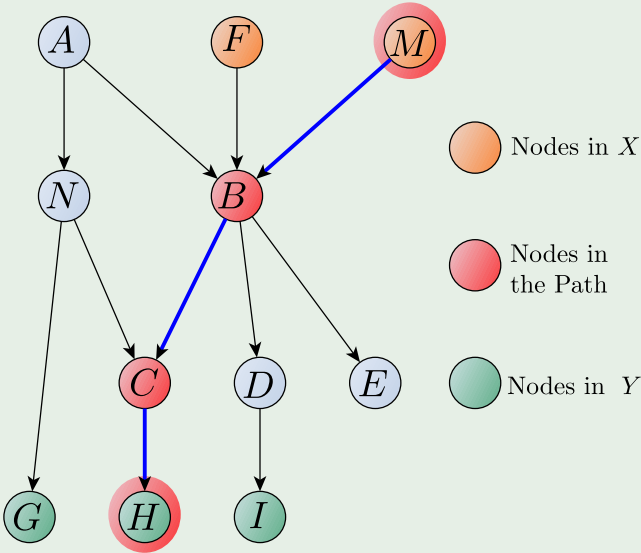
## Definition (Undirected Paths)

A path between two sets of nodes  $X$  and  $Y$  is any sequence of nodes between a member of  $X$  and a member of  $Y$  such that every adjacent pair of nodes is connected by an edge (regardless of direction) and no node appears in the sequence twice.



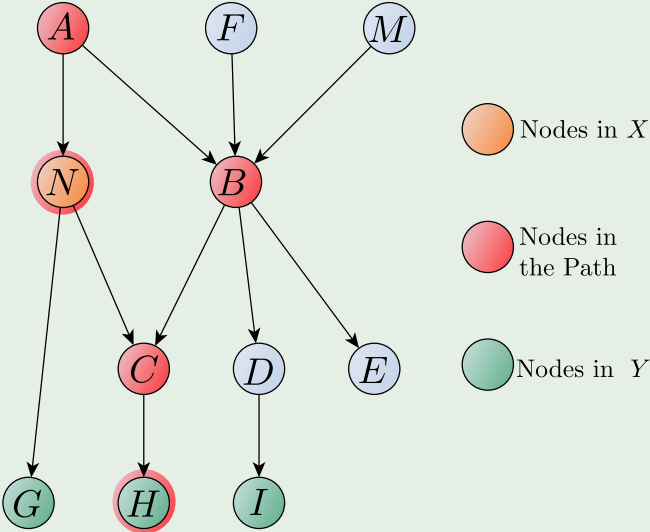
# Example

## An example



# Example

## Another one



Thus

Given a path in  $G = (V, E)$

There are the edges connecting  $[X_1, X_2, \dots, X_k]$ .

Therefore

Given the directed edge  $X \rightarrow Y$ , we say the tail of the edge is at  $X$  and the head of the edge is  $Y$ .



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# Basic Classifications of Meetings

## Head-to-Tail

A path  $X \rightarrow Y \rightarrow Z$  is a **head-to-tail meeting**, the edges meet head-to-tail at  $Y$ , and  $Y$  is a head-to-tail node on the path.

## Tail-to-Tail

A path  $X \leftarrow Y \rightarrow Z$  is a **tail-to-tail meeting**, the edges meet tail-to-tail at  $Z$ , and  $Z$  is a tail-to-tail node on the path.

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A path  $X \rightarrow Y \leftarrow Z$  is a **head-to-head meeting**, the edges meet head-to-head at  $Y$ , and  $Y$  is a head-to-head node on the path.



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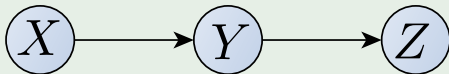
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# Examples

## Head-to-Tail



$X$  : Low Pressure

$Y$  : Rain

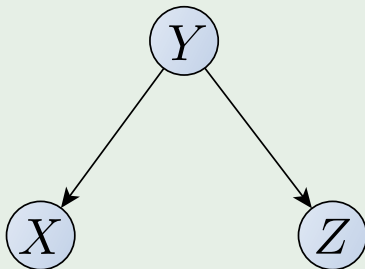
$Z$  : Traffic



# Examples

## Tail-to-Tail

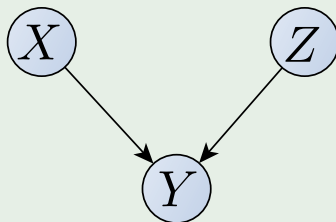
$X$  : John Calls  
 $Y$  : Alarm  
 $Z$  : Mary Calls



# Examples

## Head-to-Head

$X$  : Raining  
 $Y$  : Traffic  
 $Z$  : Ballgame



# Basic Classifications of Meetings

## Finally

- A path (undirected)  $X - Z - Y$  , such that  $X$  and  $Y$  are not adjacent, is an uncoupled meeting.





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# Blocking Information $\approx$ Conditional Independence

## Definition 2.2

Definition 2.2 Let  $G = (V, E)$  be a DAG,  $A \subseteq V$ ,  $X$  and  $Y$  be distinct nodes in  $V - A$ , and  $\rho$  be a path between  $X$  and  $Y$ .

Then  $\rho$  is blocked by  $A$  if one of the following holds:

- 1 There is a node  $Z \in A$  on the path  $\rho$ , and the edges incident to  $Z$  on  $\rho$  meet head-to-tail at  $Z$ .
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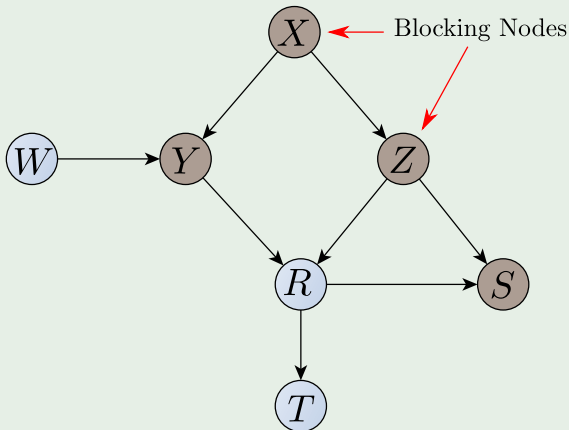
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## Example

We have that the path  $[Y, X, Z, S]$  is blocked by  $\{X\}$  and  $\{Z\}$

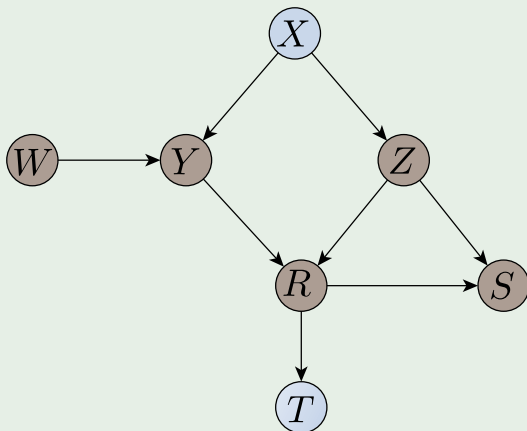
- Because the edges on the chain incident to  $X$  meet tail-to-tail at  $X$ .



## Example

We have that the path  $[W, Y, R, Z, S]$  is blocked by  $\emptyset$

- Because  $R \notin \emptyset$  and  $T \notin \emptyset$  and the edges on the chain incident to  $R$  meet head-to-head at  $R$ .





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# Definition of D-Separation

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Let  $G = (V, E)$  be a DAG,  $A \subseteq V$ , and  $X$  and  $Y$  be distinct nodes in  $V - A$ . We say  $X$  and  $Y$  are **D-Separated** by  $A$  in  $G$  if every path between  $X$  and  $Y$  is **blocked** by  $A$ .

## Definition 2.4

Let  $G = (V, E)$  be a DAG, and  $A$ ,  $B$ , and  $C$  be mutually disjoint subsets of  $V$ . We say  $A$  and  $B$  are d-separated by  $C$  in  $G$  if for every  $X \in A$  and  $Y \in B$ ,  $X$  and  $Y$  are **D-Separated** by  $C$ .

We write

$$I_G(A, B|C) \text{ or } A \perp B|C \quad (8)$$

If  $C = \emptyset$ , we write only  $I_G(A, B)$  or  $A \perp B$ .

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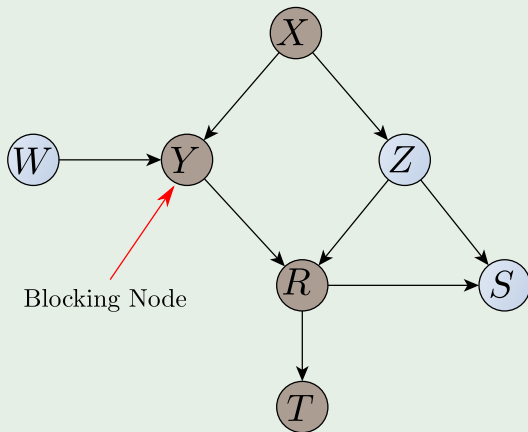
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### $X$ and $T$ are D-Separated by $\{Y, Z\}$

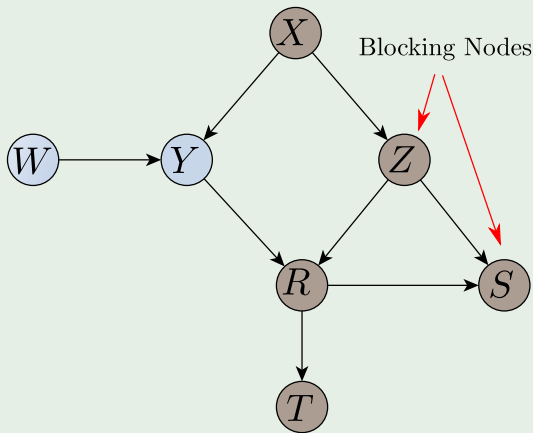
- Because the chain  $[X, Y, R, T]$  is blocked at  $Y$ .



## Example

$X$  and  $T$  are D-Separated by  $\{Y, Z\}$  - It is the set that block all paths

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# D-Separation $\Rightarrow$ Independence

## D-Separation Theorem

Let  $P$  be a probability distribution of the variables in  $V$  and  $G = (V, E)$  be a DAG. Then  $(G, P)$  satisfies the Markov condition if and only if

- for every three mutually disjoint subsets  $A, B, C \subseteq V$ , whenever  $A$  and  $B$  are D-Separated by  $C$ ,  $A$  and  $B$  are conditionally independent in  $P$  given  $C$ .



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That is,  $(G, P)$  satisfies the Markov condition if and only if

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# Proof

The proof that, if  $(G, P)$  satisfies the Markov condition

Then, each D-Separation implies the corresponding conditional independence is quite lengthy and can be found in [Verma and Pearl, 1990] and in [Neapolitan, 1990].

Then, we will only prove the other direction:

Suppose each D-Separation implies a conditional independence.

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# Proof

## Something Notable

It is not hard to see that a node's parents D-Separate the node from all its non-descendent's that are not its parents.

### Things

If we denote the sets of parents and non-descendent's of  $X$  by  $PA_X$  and  $ND_X$  respectively, we have

$$I_G(\{X\}, ND_X - PA_X | PA_X) \quad (11)$$

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If we denote the sets of parents and non-descendent's of  $X$  by  $PA_X$  and  $ND_X$  respectively, we have

$$I_G(\{X\}, ND_X - PA_X | PA_X) \quad (11)$$

## Thus

$$I_P(\{X\}, ND_X - PA_X | PA_X) \quad (12)$$



# Proof

This states the same than

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Meaning

The Markov condition is satisfied.





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# Every Entailed Conditional Independence is Identified by D-Separation

## Lemma 2.2

Any conditional independence entailed by a DAG, based on the Markov condition, is equivalent to a conditional independence among disjoint sets of random variables.

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Based on the Markov condition, a DAG  $G$  entails all and only those conditional independences that are identified by D-Separations in  $G$ .



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We would like to find the D-Separations

Since d-separations entail conditional independencies.

We want an efficient algorithm

For determining whether two sets are D-Separated by another set.

For this we need to build an algorithm

One that can find all D-Separated nodes from one set of nodes by another.



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To accomplish this

We will first find every node  $X$  such that there is at least one active path given  $A$  between  $X$  and a node in  $D$ .

Something like



Cinvestav

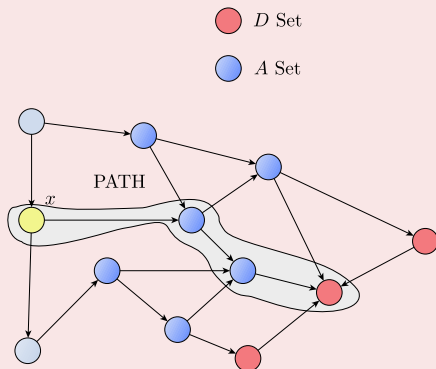


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Suppose we have a directed graph

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We can find the set  $R$  of all nodes reachable from  $x$  as follows

Any node  $V$  such that the edge  $x \rightarrow v$  exists is reachable.

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Next for each such  $v$

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We label each such edge with a 2

And keep going!!!

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If there is an active path  $\rho$  between node  $X$  and some other node  
Then every 3-node sub-path  $u - v - w$  ( $u \neq w$ ) of  $\rho$  has the following property.

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Reachable nodes from  $X$  when  $A = \emptyset$ , thus

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Only the rule 1 is applicable.





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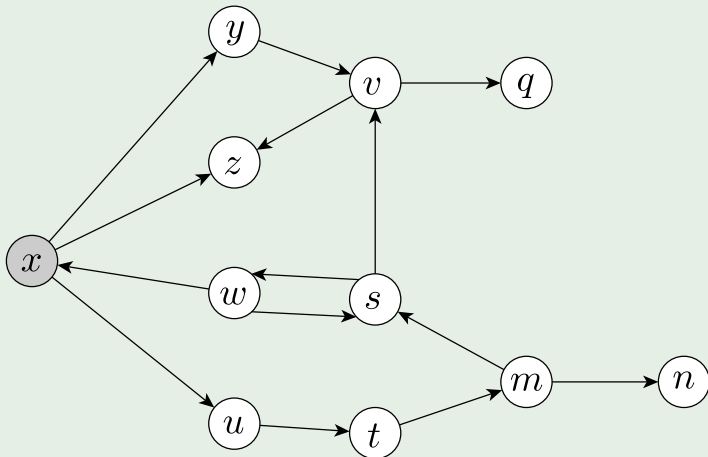
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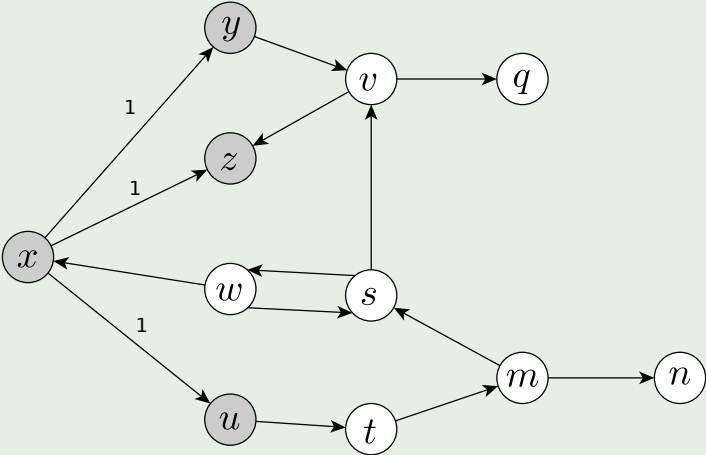
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Labeling edges to 1 and shaded nodes are in  $R$



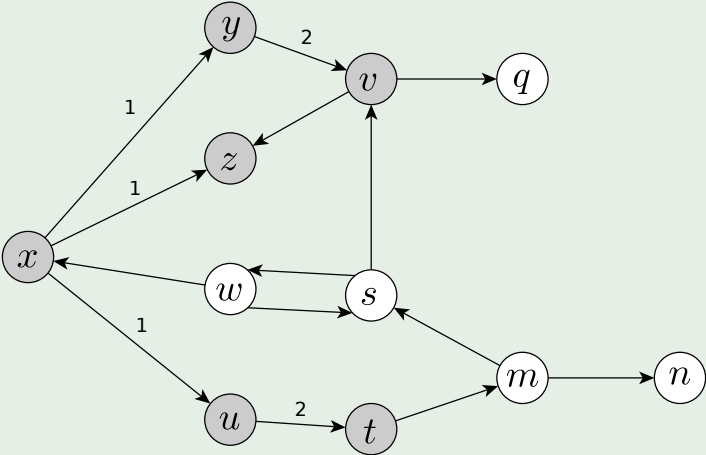
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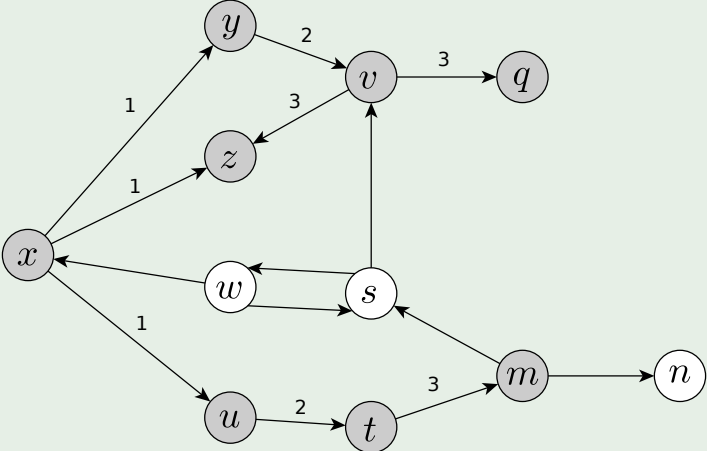
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Labeling edges to 2 and shaded nodes are in  $R$



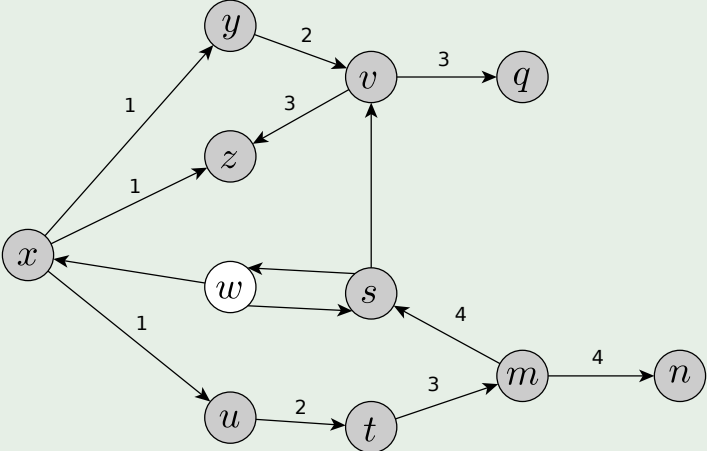
# Example

Labeling edges to 3 and shaded nodes are in  $R$



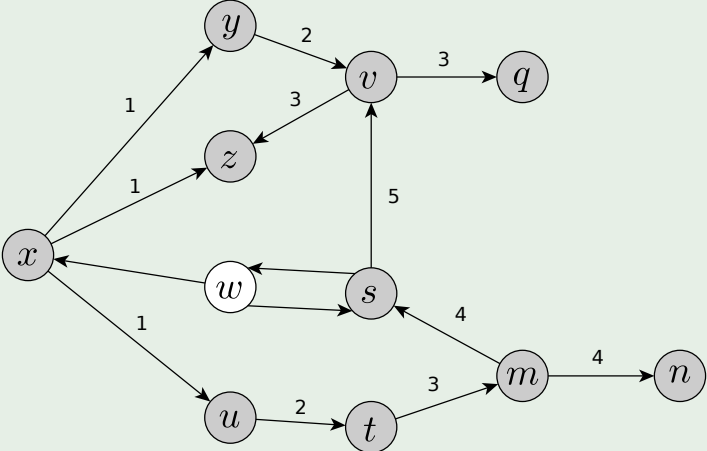
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Labeling edges to 4 and shaded nodes are in  $R$



# Example

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# Algorithm to Finding Reachability

**find-reachable-nodes**( $G$ , set of nodes  $B$ , set of nodes  $\&R$ )

**Input:**  $G = (V, E)$ , subset  $B \subset V$  and a RULE to find if two consecutive edges are legal

**Output:**  $R \subset V$  of all nodes reachable from  $B$

1. for each  $x \in B$
2.     add  $x$  to  $R$
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## The following steps

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# Complexity of find-reachable-nodes

We have that

Let  $n$  be the number of nodes and  $m$  be the number of edges.

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In the worst case, each of the nodes can be reached from  $n$  entry points.

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# Algorithm for D-separation

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Separations(*DAG*  $G = (V, E)$ , set of nodes  $A, B$ , set of nodes  $D$ )

**Input:**  $G = (V, E)$  and two disjoint subsets  $A, B \subset V$

**Output:**  $D \subset V$  containing all nodes D-Separated from every node in  $B$  by  $A$ . That is  $I_G(B, D | A)$  holds and no superset  $D$  has this property.

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12. Run the algorithm:

$find\_reachable\_nodes(G', B, R)$

    ▷ Note  $B \subseteq R$

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12. Run the algorithm:

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    ▷ Note  $B \subseteq R$

13. return  $D = V - (A \cup R)$

# Algorithm for D-separation

## Find-D-

Separations(*DAG*  $G = (V, E)$ , set of nodes  $A, B$ , set of nodes  $D$ )

**Input:**  $G = (V, E)$  and two disjoint subsets  $A, B \subset V$

**Output:**  $D \subset V$  containing all nodes D-Separated from every node in  $B$  by  $A$ . That is  $I_G(B, D | A)$  holds and no superset  $D$  has this property.

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We can implement the construction of *descendent* [ $v$ ] as follow

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The E' is necessary because using only the RULE on E will no get us all the active paths.

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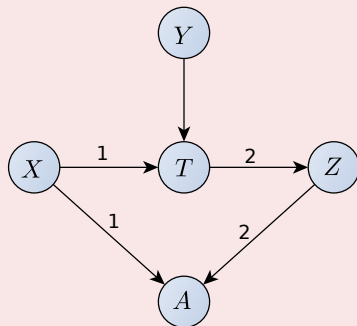
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Given  $A$  is the only node in  $A$  and  $X \rightarrow T$  is the only edge in  $B$ , the edges in that DAG are numbered according to the method.

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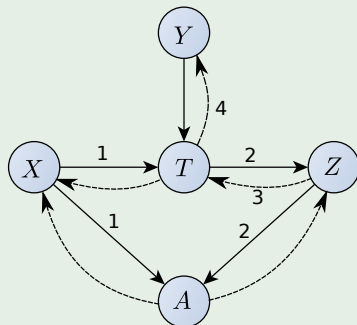
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Thus

Once, we add the extra edges, we get



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# Complexity

Please take a look at page 81 at

“Learning Bayesian Networks” by Richard E. Neapolitan.

For the analysis of the algorithm for  $m$  edges and  $n$  nodes

$$\Theta(m) \text{ with } m \geq n. \quad (16)$$



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# The D-Separation Algorithm works

## Theorem 2.2

The set  $D$  contains all and only nodes D-Separated from every node in  $B$  by  $A$ .

- That is, we have  $I_G(B, D | A)$  and no superset of  $D$  has this property.

## Proof

- The set  $R$  determined by the algorithm contains
  - ▶ All nodes in  $B$ .
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For any two nodes  $x \in B$  and  $y \notin A \cup B$

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Thus  $R$  contains the nodes in  $B$  plus all and only those nodes that have active paths between them and a node in  $B$ .

By the definition of D-Separation

A node is D-Separated from every node in  $B$  in  $A$  if the node is not in  $A \cup B$  and there is not active path between the node and a node in  $B$ .



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Equivalent Definition of D-Separation

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Thus

$D = V - (A \cup R)$  is the set of all nodes D-Separated from every node in B by A.





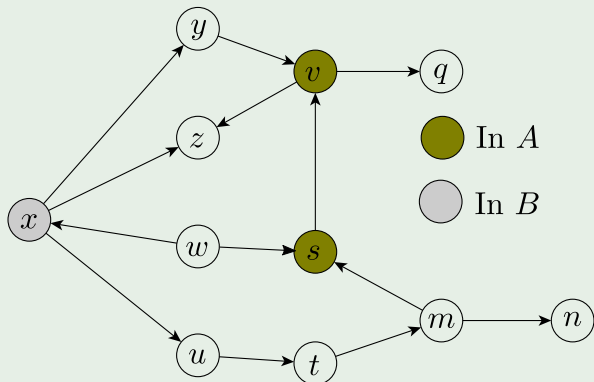
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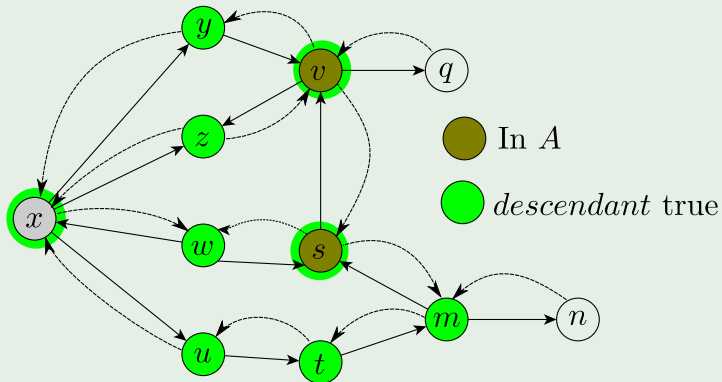
# Example

$B = \{x\}$  and  $A = \{s, v\}$ - Original Graph!!!



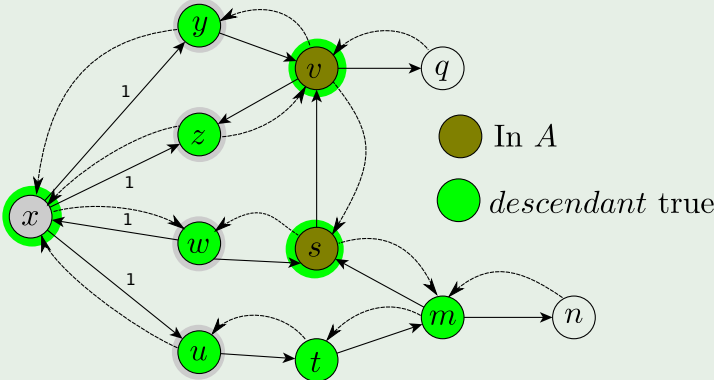
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$B = \{x\}$  and  $A = \{s, v\}$ - Moralized and with the tracking of descendants



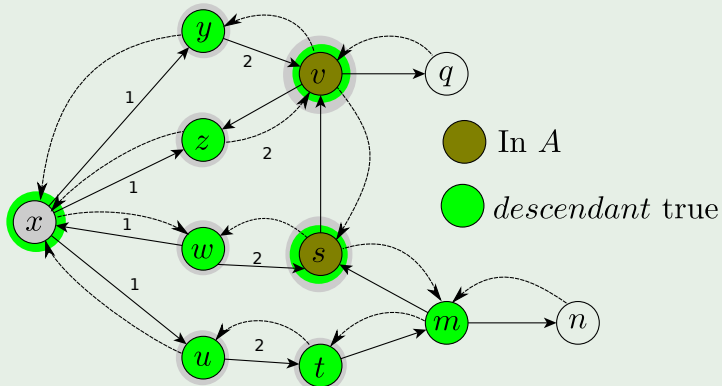
# Example

$B = \{x\}$  and  $A = \{s, v\}$  and the first part of the reachability algorithm



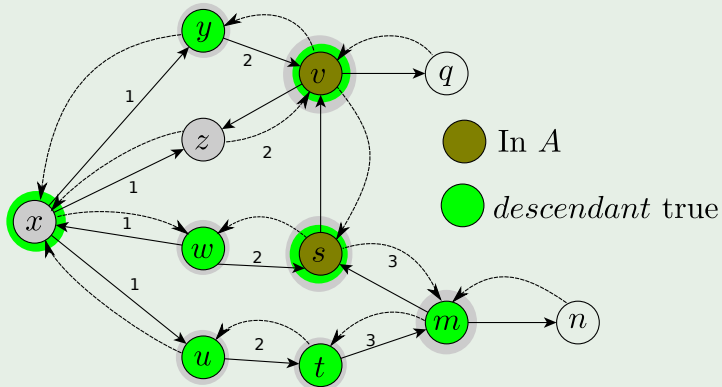
# Example

Remember that Legality is in  $G$



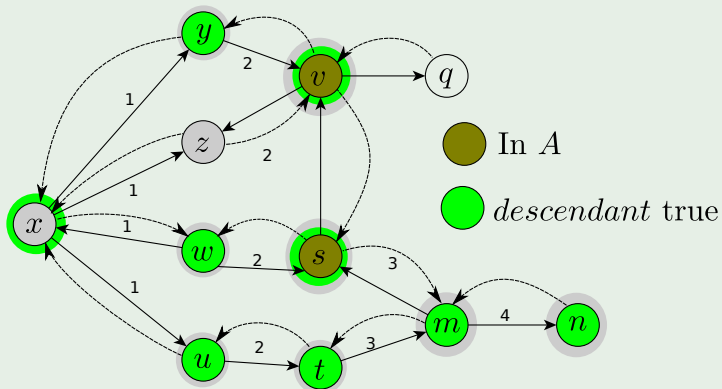
# Example

Now, we have that



# Example

$$D - \{A \cup R\} = \{q\}$$



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# Application

## Something Notable

In general, the inference problem in Bayesian networks is to determine  $P(B|A)$ , where  $A$  and  $B$  are two sets of variables.

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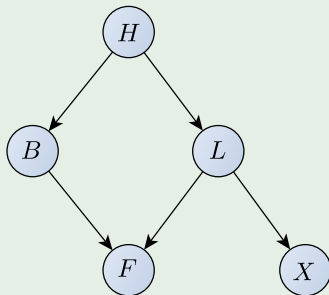
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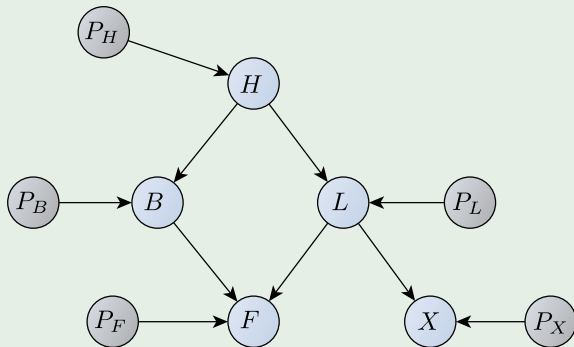
# Example

Given the following the DAG  $G$



# Example

We generate  $G'$



# Where

The extra nodes represent

The probabilities in the interval  $[0, 1]$  and representing  $P(X = x)$

Creating a set of  $P$  as the set of auxiliary parent nodes

Thus, if we want to determine  $P(B|A)$  in  $G$ , we can use the algorithm for D-Separation to find  $D$ .

Such that

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And no superset of  $D$  has this property, then take  $D \cap P$ .



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## For example

We want  $P(f)$

To determine it we need that all and only the values of  $P_H$ ,  $P_B$ ,  $P_L$ , and  $P_F$

Because

$$I_G(\{F\}, \{P_X\} | \emptyset) \quad (18)$$

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$P_X$  is the only auxiliary parent variable D-Separated from  $\{F\}$  by the empty set.





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- Topologies may happen to encode causal structure.

• Topologies are only guaranteed to encode conditional independence!



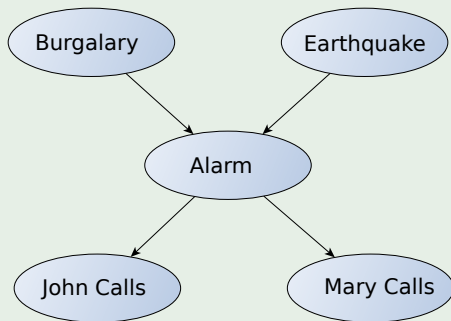
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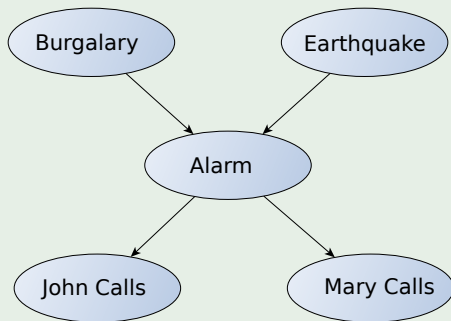


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New Network



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