# Introduction to Artificial Intelligence Introduction to Bayesian Networks 

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## Outline

## (1) Introduction

- The History of Bayesian Applications
- Bayes Theorem
- Everything Starts at Someplace
- Why Bayesian Networks?
(2) Bayesian Networks
- Definition
- Markov Condition
- Example
- Using the Markov Condition
- Representing the Joint Distribution
- Example
- Observations
- Markov Condition and DAG's
- Example
- Causality and Bayesian Networks
- Precautionary Tale
- Causal DAG
- The Causal Markov Condition
- Inference in Bayesian Networks
- Example
- General Strategy of Inference
- Inference - An Overview


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## Summary until mid '80s

- "Pure logic will solve the Al problems!"
- "Probability theory is intractable to use and too complicated for complex models."


## But...

## More History

- 1986 Bayesian networks were revived and reintroduced to expert systems (Pearl).


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- 1999 Bayesian Networks are getting more and more used. Ex. Gene expression analysis, Business strategy etc.
- 2000 Widely used - A Bayesian Network tool will be shipped with every Windows ${ }^{\text {TM }}$ Commercial Server.


## Furtheron 2000-2015

Bayesian Networks are use in

- Spam Detection.
- Gene Discovery.
- Signal Processing.
- Ranking.
- Forecasting.
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## Something Notable

We are interested more and more on building automatically Bayesian Networks using data!!!

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## Many of Them

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(2) When used for learning casual relationships, they help better understand a problem domain as well as forecast consequences.
(3) it is ideal to use a Bayesian network for representing prior data and knowledge.
(9) Over-fitting of data can be avoidable when using Bayesian networks and Bayesian statistical methods.

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## Bayes Theorem

## One Version

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P(A \mid B)=\frac{P(B \mid A) P(A)}{P(B)}
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- $P(B \mid A)$ is the conditional probability of B given A . It is also called the likelihood.
- $P(B)$ is the prior or marginal probability of B , and acts as a normalizing constant.


## A Simple Example

Consider two related variables:
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- $P(T=+v e \mid D=n)=0.01$


## A Simple Example

What is the probability that a person has taken the drug?

$$
P(D=y \mid T=+v e)=\frac{P(T=+v e \mid D=y) P(D=\mathrm{y})}{P(T=+v e \mid D=y) P(D=\mathrm{y})+P(T=+v e \mid D=n) P(D=\mathrm{n})}
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## Let me develop the equation

Using simply

$$
\begin{equation*}
P(A, B)=P(A \mid B) P(B) \text { (Chain Rule) } \tag{1}
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$$

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## A More Complex Case

## Increase Complexity

- Suppose now that there is a similar link between Lung Cancer $(L)$ and a chest $X$-ray $(X)$ and that we also have the following relationships:


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- History of smoking $(S)$ has a direct influence on bronchitis $(B)$ and lung cancer ( $L$ );


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- History of smoking $(S)$ has a direct influence on bronchitis $(B)$ and lung cancer ( $L$ );
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## Question

- What is the probability that someone has bronchitis given that they smoke, have fatigue and have received a positive X-ray result?


## A More Complex Case

## Short Hand

$$
P\left(b_{1} \mid s_{1}, f_{1}, x_{1}\right)=\frac{P\left(b_{1}, s_{1}, f_{1}, x_{1}\right)}{P\left(s_{1}, f_{1}, x_{1}\right)}=\frac{\sum_{l} P\left(b_{1}, s_{1}, f_{1}, x_{1}, l\right)}{\sum_{b, l} P\left(b, s_{1}, f_{1}, x_{1}, l\right)}
$$

## Values for the Complex Case

## Table

| Feature | Value | When the Feature Takes this Value |
| :---: | :---: | :---: |
| $H$ | $h_{1}$ | There is a history of smoking <br> There is no history of smoking |
| $B$ | $h_{2}$ | $b_{1}$ | Bronchitis is present | Bronchitis is absent |  |
| :---: | :---: |
|  | $b_{2}$ |

## Problem with Large Instances

The joint probability distribution $P(H, B, L, F, C)$

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－To obtain posterior distributions once some evidence is available requires summation over an exponential number of terms！！！

## Ok！！！

－We need something BETTER！！！

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## Bayesian Networks

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## This allows to define

- Conditional Probability Specifications:
- The conditional probability of each variable given its parents in the DAG.


## Example

## DAG for the previous Lung Cancer Problem



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## Notation

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## Notation

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## We use the following the notation

$$
I_{P}\left(\{X\}, N D_{X} \mid P A_{X}\right)
$$

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## Example

## We have that



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Given the previous DAG we have

| Node | PA | Conditional Independence |
| :---: | :---: | :---: |
| $C$ | $\{L\}$ | $I_{P}(\{C\},\{H, B, F\} \mid\{L\})$ |
| $B$ | $\{H\}$ | $I_{P}(\{B\},\{L, C\} \mid\{H\})$ |
| $F$ | $\{B, L\}$ | $I_{P}(\{F\},\{H, C\} \mid\{B, L\})$ |
| $L$ | $\{H\}$ | $I_{P}(\{L\},\{B\} \mid\{H\})$ |

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## Using the Markov Condition

First Decompose a Joint Distribution using the Chain Rule

$$
\begin{equation*}
P(c, f, l, b, h)=P(c \mid b, s, l, f) P(f \mid b, h, l) P(l \mid b, h) P(b \mid h) P(h) \tag{2}
\end{equation*}
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Using the Markov condition in the following DAG


We have the following equivalences

- $P(c \mid b, h, l, f)=P(c \mid l)$
- $P(f \mid b, h, l)=P(f \mid b, l)$
- $P(l \mid b, h)=P(l \mid h)$


## Using the Markov Condition

## Finally

$$
\begin{equation*}
P(c, f, l, b, h)=P(c \mid l) P(f \mid b, l) P(l \mid h) P(b \mid h) P(h) \tag{3}
\end{equation*}
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## Representing the Joint Distribution

## Theorem (Product of Conditional Probabilities of the Parents)

If $(G, P)$ satisfies the Markov condition, then $P$ is equal to the product of its conditional distributions of all nodes given values of their parents, whenever these conditional distributions exist.

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## General Representation

- In general, for a network with nodes $X_{1}, X_{2}, \ldots, X_{n} \Rightarrow$

$$
P\left(x_{1}, x_{2}, \ldots, x_{n}\right)=\prod_{i=1}^{n} P\left(x_{i} \mid P A\left(x_{i}\right)\right)
$$

## Proof

We prove the case where $P$ is discrete
Order the nodes so that if $Y$ is a descendant of $Z$, then $Y$ follows $Z$ in the ordering.

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This is called
Ancestral ordering.

## Proof

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The ancestral ordering are

$$
\begin{equation*}
[H, L, B, C, F] \text { and }[H, B, L, F, C] \tag{4}
\end{equation*}
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Let $X_{1}, X_{2}, \ldots, X_{n}$ be the resultant ordering.

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Let $X_{1}, X_{2}, \ldots, X_{n}$ be the resultant ordering.
For a given set of values of $x_{1}, x_{2}, \ldots, x_{n}$
Let $\mathrm{pa}_{i}$ be the subsets of these values containing the values of $X_{i}^{\prime} s$ parents

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Let $X_{1}, X_{2}, \ldots, X_{n}$ be the resultant ordering.
For a given set of values of $x_{1}, x_{2}, \ldots, x_{n}$
Let $\mathrm{pa}_{i}$ be the subsets of these values containing the values of $X_{i}^{\prime} s$ parents

Thus, we need to prove that whenever $P\left(\mathrm{pa}_{i}\right) \neq 0$ for $1 \leq i \leq n$

$$
\begin{equation*}
P\left(x_{n}, x_{n-1}, \ldots, x_{1}\right)=P\left(x_{n} \mid \mathrm{pa}_{n}\right) P\left(x_{n-1} \mid \mathrm{pa}_{n-1}\right) \ldots P\left(x_{1} \mid \mathrm{pa}_{1}\right) \tag{5}
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- Assume then $P\left(\mathrm{pa}_{i}\right) \neq 0$ for $1 \leq i \leq n$ for a combination of $x_{i}^{\prime} s$ values.


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\begin{equation*}
P\left(x_{1}\right)=P\left(x_{1} \mid \mathrm{pa}_{1}\right) \tag{6}
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## Inductive Hypothesis

Suppose for this combination of values of the $x_{i}{ }^{\prime} s$ that

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## Something Notable

We show this using induction on the number of variables in the network.

- Assume then $P\left(\mathrm{pa}_{i}\right) \neq 0$ for $1 \leq i \leq n$ for a combination of $x_{i}^{\prime} s$ values.


## Base Case of Induction

Since $\mathrm{pa}_{1}$ is empty, then

$$
\begin{equation*}
P\left(x_{1}\right)=P\left(x_{1} \mid \mathrm{pa}_{1}\right) \tag{6}
\end{equation*}
$$

## Inductive Hypothesis

Suppose for this combination of values of the $x_{i}{ }^{\prime} s$ that

$$
\begin{equation*}
P\left(x_{i}, x_{i-1}, \ldots, x_{1}\right)=P\left(x_{i} \mid \mathrm{pa}_{i}\right) P\left(x_{i-1} \mid \mathrm{pa}_{i-1}\right) \ldots P\left(x_{1} \mid \mathrm{pa}_{1}\right) \tag{7}
\end{equation*}
$$

## Proof

## Inductive Step

We need show for this combination of values of the $x_{i}$ 's that

$$
\begin{equation*}
P\left(x_{i+1}, x_{i}, \ldots, x_{1}\right)=P\left(x_{i+1} \mid \mathrm{pa}_{i+1}\right) P\left(x_{i} \mid \mathrm{pa}_{i}\right) \ldots P\left(x_{1} \mid \mathrm{pa}_{1}\right) \tag{8}
\end{equation*}
$$

## Proof

## Inductive Step

We need show for this combination of values of the $x_{i}$ 's that

$$
\begin{equation*}
P\left(x_{i+1}, x_{i}, \ldots, x_{1}\right)=P\left(x_{i+1} \mid \mathrm{pa}_{i+1}\right) P\left(x_{i} \mid \mathrm{pa}_{i}\right) \ldots P\left(x_{1} \mid \mathrm{pa}_{1}\right) \tag{8}
\end{equation*}
$$

## Case 1

For this combination of values:

$$
\begin{equation*}
P\left(x_{i}, x_{i-1}, \ldots, x_{1}\right)=0 \tag{9}
\end{equation*}
$$

## Proof

## Inductive Step

We need show for this combination of values of the $x_{i}$ 's that

$$
\begin{equation*}
P\left(x_{i+1}, x_{i}, \ldots, x_{1}\right)=P\left(x_{i+1} \mid \mathrm{pa}_{i+1}\right) P\left(x_{i} \mid \mathrm{pa}_{i}\right) \ldots P\left(x_{1} \mid \mathrm{pa}_{1}\right) \tag{8}
\end{equation*}
$$

## Case 1

For this combination of values:

$$
\begin{equation*}
P\left(x_{i}, x_{i-1}, \ldots, x_{1}\right)=0 \tag{9}
\end{equation*}
$$

## By Conditional Probability, we have

$$
\begin{equation*}
P\left(x_{i+1}, x_{i}, \ldots, x_{1}\right)=P\left(x_{i+1} \mid x_{i}, \ldots, x_{1}\right) P\left(x_{i}, \ldots, x_{1}\right)=0 \tag{10}
\end{equation*}
$$

## Proof

Due to the previous equalities and the inductive hypothesis
There is some $k, 1 \leq k \leq i$ such that $P\left(x_{k} \mid \mathrm{pa}_{k}\right)=0$ because after all

$$
\begin{equation*}
P\left(x_{i} \mid \mathrm{pa}_{i}\right) P\left(x_{i-1} \mid \mathrm{pa}_{i-1}\right) \ldots P\left(x_{1} \mid \mathrm{pa}_{1}\right)=0 \tag{11}
\end{equation*}
$$

## Proof

Due to the previous equalities and the inductive hypothesis
There is some $k, 1 \leq k \leq i$ such that $P\left(x_{k} \mid \mathrm{pa}_{k}\right)=0$ because after all

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\end{equation*}
$$

## Thus, the equality holds

Now for the Case 2

## Proof

## Due to the previous equalities and the inductive hypothesis

There is some $k, 1 \leq k \leq i$ such that $P\left(x_{k} \mid \mathrm{pa}_{k}\right)=0$ because after all

$$
\begin{equation*}
P\left(x_{i} \mid \mathrm{pa}_{i}\right) P\left(x_{i-1} \mid \mathrm{pa}_{i-1}\right) \ldots P\left(x_{1} \mid \mathrm{pa}_{1}\right)=0 \tag{11}
\end{equation*}
$$

## Thus, the equality holds

Now for the Case 2

## Case 2

For this combination of values $P\left(x_{i}, x_{i-1}, \ldots, x_{1}\right) \neq 0$

## Proof

## Thus by the Rule of Conditional Probability

$$
P\left(x_{i+1}, x_{i}, \ldots, x_{1}\right)=P\left(x_{i+1} \mid x_{i}, \ldots, x_{1}\right) P\left(x_{i}, \ldots, x_{1}\right)
$$

## Proof

## Thus by the Rule of Conditional Probability

$$
P\left(x_{i+1}, x_{i}, \ldots, x_{1}\right)=P\left(x_{i+1} \mid x_{i}, \ldots, x_{1}\right) P\left(x_{i}, \ldots, x_{1}\right)
$$

## Definition Markov Condition (Remember!!!)

- Suppose we have a joint probability distribution $P$ of the random variables in some set $V$ and a DAG $G=(V, E)$.


## Proof

## Thus by the Rule of Conditional Probability

$$
P\left(x_{i+1}, x_{i}, \ldots, x_{1}\right)=P\left(x_{i+1} \mid x_{i}, \ldots, x_{1}\right) P\left(x_{i}, \ldots, x_{1}\right)
$$

## Definition Markov Condition (Remember!!!)

- Suppose we have a joint probability distribution $P$ of the random variables in some set $V$ and a DAG $G=(V, E)$.
- We say that $(G, P)$ satisfies the Markov condition if for each variable $X \in V,\{X\}$ is conditionally independent of the set of all its non-descendents given the set of all its parents.


## Proof

## Given this Markov Condition and the fact that $X_{1}, \ldots, X_{i}$ are all non-descendants of $X_{i+1}$

We have that

$$
P\left(x_{i+1}, x_{i}, \ldots, x_{1}\right)=P\left(x_{i+1} \mid \mathrm{pa}_{i+1}\right) P\left(x_{i}, \ldots, x_{1}\right)
$$

## Proof

## Given this Markov Condition and the fact that $X_{1}, \ldots, X_{i}$ are all non-descendants of $X_{i+1}$

We have that

$$
\begin{align*}
P\left(x_{i+1}, x_{i}, \ldots, x_{1}\right) & =P\left(x_{i+1} \mid \mathrm{pa}_{i+1}\right) P\left(x_{i}, \ldots, x_{1}\right) \\
& =P\left(x_{i+1} \mid \mathrm{pa}_{i+1}\right) P\left(x_{i} \mid \mathrm{pa}_{i}\right) \cdots P\left(x_{1} \mid \mathrm{pa}_{1}\right) \tag{IH}
\end{align*}
$$

Q.E.D.

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## Example

## Imagine the following Random Variables

| Variable | Value | Outcome |
| :---: | :---: | :---: |
| $V$ | $v_{1}$ | All objects containing a '1' |
|  | $v_{2}$ | All objects containing a '2' |
| $S$ | $s_{1}$ | All square objects |
|  | $s_{2}$ | All round objects |
| $C$ | $c_{1}$ | All black objects |
|  | $c_{2}$ | All white objects |

## Example

## Using the following graph



## Example

## Using the following graph



## Using the chain rule

$$
\begin{aligned}
P(v, s, c) & =P(v \mid s, c) P(s \mid c) P(c) \\
& =P(v \mid c) P(s \mid c) P(c)
\end{aligned}
$$

Then, using the following probabilities
We have

# 1 <br> 1 2 2 2 2 <br> - <br> 2 <br>  

| $c$ | $s$ | $v$ | $P(v \mid s, c)$ | $P(v \mid c)$ |
| :---: | :---: | :---: | :---: | :---: |
| $c_{1}$ | $s_{1}$ | $v_{1}$ | $1 / 3$ | $1 / 3$ |
| $c_{1}$ | $s_{1}$ | $v_{2}$ | $2 / 3$ | $2 / 3$ |
| $c_{1}$ | $s_{2}$ | $v_{1}$ | $1 / 3$ | $1 / 3$ |
| $c_{1}$ | $s_{2}$ | $v_{2}$ | $2 / 3$ | $2 / 3$ |
| $c_{2}$ | $s_{1}$ | $v_{1}$ | $1 / 2$ | $1 / 2$ |
| $c_{2}$ | $s_{1}$ | $v_{2}$ | $1 / 2$ | $1 / 2$ |
| $c_{2}$ | $s_{2}$ | $v_{1}$ | $1 / 2$ | $1 / 2$ |
| $c_{2}$ | $s_{2}$ | $v_{2}$ | $1 / 2$ | $1 / 2$ |

## Therefore

We have the following probabilities

$$
P\left(c_{1}, s_{1}, v_{1}\right)=\frac{2}{13}
$$

## Therefore

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$$
P\left(c_{1}, s_{1}, v_{1}\right)=\frac{2}{13}
$$

## With the following using the Markov Condition

$$
\begin{aligned}
P\left(v_{1} \mid c_{1}\right) P\left(s_{1} \mid c_{1}\right) P\left(c_{1}\right) & =P(\text { One } \mid \text { Black }) P(\text { Square } \mid \text { Black }) P(\text { Black }) \\
& =\frac{1}{3} \times \frac{2}{3} \times \frac{9}{13}=\frac{2}{13}
\end{aligned}
$$

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Markov Condition and DAG's
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```
        Causality and Bayesian Networks
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## Now

## OBSERVATIONS

- There are good savings in the Number of Values


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## Brute Force Approach

- on $n$ binary variables requires $m^{n}$, if $m=\max \left\{\left|v_{i}\right| \mid V\right\}_{i=1}^{n}$.


## OBSERVATIONS

- There are good savings in the Number of Values


## Brute Force Approach

- on $n$ binary variables requires $m^{n}$, if $m=\max \left\{\left|v_{i}\right| \mid V\right\}_{i=1}^{n}$.

For a Bayesian Network with $n$ binary variables and each node has at most $k$ parents

- Then, less than $m^{k} n$ values are required!!!


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## It is more!!!

## Theorem (Markov Condition on a DAG)

- Let a DAG $G$ be given in which each node is a random variable, and let a discrete conditional probability distribution of each node given values of its parents in $G$ be specified.


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- Let a DAG $G$ be given in which each node is a random variable, and let a discrete conditional probability distribution of each node given values of its parents in $G$ be specified.
- Then, the product of these conditional distributions yields a joint probability distribution $P$ of the variables, and $(G, P)$ satisfies the Markov condition.


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## Note

- Notice that the theorem requires that specified conditional distributions be discrete.


## It is more！！！

## Theorem（Markov Condition on a DAG）

－Let a DAG $G$ be given in which each node is a random variable，and let a discrete conditional probability distribution of each node given values of its parents in $G$ be specified．
－Then，the product of these conditional distributions yields a joint probability distribution $P$ of the variables，and $(G, P)$ satisfies the Markov condition．

## Note

－Notice that the theorem requires that specified conditional distributions be discrete．
－Often in the case of continuous distributions it still holds．

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## Example

## We have the following DAG and probabilities

$$
\begin{array}{lll}
P\left(x_{1}\right)=0.3 & P\left(y_{1} \mid x_{1}\right)=0.6 & P\left(z_{1} \mid y_{1}\right)=0.2 \\
P\left(x_{2}\right)=0.7 & P\left(y_{2} \mid x_{1}\right)=0.4 & P\left(z_{2} \mid y_{1}\right)=0.8 \\
& P\left(y_{1} \mid x_{2}\right)=0.0 & P\left(z_{1} \mid y_{2}\right)=0.5 \\
P\left(y_{2} \mid x_{2}\right)=1.0 & P\left(z_{2} \mid y_{2}\right)=0.5
\end{array}
$$

## Then

We have the according to a Markov Condition on a DAG

$$
P(x, y, z)=P(z \mid y) P(y \mid x) P(x)
$$

We have the according to a Markov Condition on a DAG

$$
P(x, y, z)=P(z \mid y) P(y \mid x) P(x)
$$

## Which, we have that

- It satisfies the Markov Condition.


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## Causality in Bayesian Networks

## Definition of a Cause

The one, such as a person, an event, or a condition, that is responsible for an action or a result.

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## However

- Although useful, this simple definition is certainly not the last word on the concept of causation.


## Causality in Bayesian Networks

## Definition of a Cause

The one, such as a person, an event, or a condition, that is responsible for an action or a result.

## However

- Although useful, this simple definition is certainly not the last word on the concept of causation.
- Actually Philosophers are still wrangling the issue!!!


## Causality in Bayesian Networks

## Nevertheless, It sheds light in the issue

- If the action of making variable $X$ take some value sometimes changes the value taken by a variable $Y$.



## Causality in Bayesian Networks

## Nevertheless, It sheds light in the issue

- If the action of making variable $X$ take some value sometimes changes the value taken by a variable $Y$.


Here, we assume $X$ is responsible for sometimes changing $Y$ 's value

- Thus, we conclude $X$ is a cause of $Y$.


## Furthermore

## Formally

We say we manipulate $X$ when we force $X$ to take some value.

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- We say $X$ causes $Y$ if there is some manipulation of $X$ that leads to a change in the probability distribution of $Y$.


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## Thus

We assume causes and their effects are statistically correlated.

## Furthermore

## Formally

We say we manipulate $X$ when we force $X$ to take some value.

- We say $X$ causes $Y$ if there is some manipulation of $X$ that leads to a change in the probability distribution of $Y$.


## Thus

We assume causes and their effects are statistically correlated.

## However

Variables can be correlated without one causing the other.

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## Precautionary Tale: Causality and Bayesian Networks

## Important

Not every Bayesian Networks describes causal relationships between the variables.

## Precautionary Tale: Causality and Bayesian Networks

## Important

Not every Bayesian Networks describes causal relationships between the variables.

## Consider

- Consider the dependence between Lung Cancer, $L$, and the X-ray test, $X$.


## Precautionary Tale: Causality and Bayesian Networks

## Important

Not every Bayesian Networks describes causal relationships between the variables.

## Consider

- Consider the dependence between Lung Cancer, $L$, and the X-ray test, X.
- By focusing on just these variables we might be tempted to represent them by the following Bayesian Networks.


## Precautionary Tale: Causality and Bayesian Networks

## Important

Not every Bayesian Networks describes causal relationships between the variables.

## Consider

- Consider the dependence between Lung Cancer, $L$, and the X-ray test, $X$.
- By focusing on just these variables we might be tempted to represent them by the following Bayesian Networks.



## Precautionary Tale: Causality and Bayesian Networks

## However, we can try the same

$$
\begin{aligned}
& P\left(l_{1} \mid x_{1}\right)=0.02915 \\
& P\left(l_{1} \mid x_{2}\right)=0.00041
\end{aligned} \longrightarrow X\left(x_{1}\right)=0.02058
$$

## Remark

## Be Careful

- It is tempting to think that Bayesian Networks can be created by creating a DAG where the edges represent direct causal relationships between the variables.


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## However

## Causal DAG

- Given a set of variables $V$, if for every $X, Y \in V$ we draw an edge from $X$ to $Y \Longleftrightarrow X$ is a direct cause of $Y$ relative to $V$, we call the resultant DAG a causal DAG.


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## Causal DAG

- Given a set of variables $V$, if for every $X, Y \in V$ we draw an edge from $X$ to $Y \Longleftrightarrow X$ is a direct cause of $Y$ relative to $V$, we call the resultant DAG a causal DAG.


## We want

- If we create a causal DAG $G=(V, E)$ and assume the probability distribution of the variables in $V$ satisfies the Markov condition with $G$ :


## However

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## We want

- If we create a causal DAG $G=(V, E)$ and assume the probability distribution of the variables in $V$ satisfies the Markov condition with G:
- we say we are making the causal Markov assumption.


## However

## Causal DAG

- Given a set of variables $V$, if for every $X, Y \in V$ we draw an edge from $X$ to $Y \Longleftrightarrow X$ is a direct cause of $Y$ relative to $V$, we call the resultant DAG a causal DAG.


## We want

- If we create a causal DAG $G=(V, E)$ and assume the probability distribution of the variables in $V$ satisfies the Markov condition with $G$ :
- we say we are making the causal Markov assumption.


## In General

- The Markov condition holds for a causal DAG. Holds


## Remark

There are several thing that the DAG needs to have in order to have the Markov Condition. Holds

## Remark

There are several thing that the DAG needs to have in order to have the Markov Condition.

## Examples of those

- Common Causes Holds


## Remark

There are several thing that the DAG needs to have in order to have the Markov Condition.

## Examples of those

- Common Causes
- Common Effects


## How to have a Markov Assumption : Common Causes

## Consider



## How to have a Markov Assumption : Common Causes

## Consider



## Markov condition

$$
\begin{equation*}
I_{p}(\{B\},\{L\} \mid\{S\}) \Rightarrow P(B \mid L, S)=P(B \mid S) \tag{12}
\end{equation*}
$$

## How to have a Markov Assumption : Common Causes

If we know the causal relationships

$$
S \rightarrow B \text { and } S \rightarrow L
$$

## How to have a Markov Assumption : Common Causes

If we know the causal relationships

$$
\begin{equation*}
S \rightarrow B \text { and } S \rightarrow L \tag{13}
\end{equation*}
$$

## Now!!!

- If we know that you smoke...


## How to have a Markov Assumption : Common Causes

Then, because of the blocking of information from smoking

- Finding out that Bronchitis will not give us any more information about the probability of having Lung Cancer.


## How to have a Markov Assumption : Common Causes

Then, because of the blocking of information from smoking

- Finding out that Bronchitis will not give us any more information about the probability of having Lung Cancer.


## Markov condition

- It is satisfied!!!


## How to have a Markov Assumption : Common Effects

## Consider



## How to have a Markov Assumption: Common Effects

## Consider



## Markov Condition

$$
\begin{equation*}
l_{p}(B, W) \Rightarrow P(B \mid E)=P(B) \tag{14}
\end{equation*}
$$

## How to have a Markov Assumption: Common Effects

## Consider



## Markov Condition

$$
\begin{equation*}
l_{p}(B, W) \Rightarrow P(B \mid E)=P(B) \tag{14}
\end{equation*}
$$

## Thus

We would expect Raining and Ballgame to be independent of each other which is in agreement with the Markov condition.

## How to have a Markov Assumption : Common Effects

However
We would, however expect them to be conditionally dependent given Alarm.

## How to have a Markov Assumption: Common Effects

## However

We would, however expect them to be conditionally dependent given Alarm.

## Thus

If the alarm has gone off, news that there had been an earthquake would 'explain away' the idea that a burglary had taken place.

## How to have a Markov Assumption : Common Effects

## However

We would, however expect them to be conditionally dependent given Alarm.

## Thus

If the alarm has gone off, news that there had been an earthquake would 'explain away' the idea that a burglary had taken place.

## Then

Again in agreement with the Markov condition.

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## The Causal Markov Condition

## What do we want?

The basic idea is that the Markov condition holds for a causal DAG.

## Rules to construct A Causal Graph

## Conditions

(1) There must be no hidden common causes.

## Rules to construct A Causal Graph

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(1) There must be no hidden common causes.
(2) There must not be selection bias.

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(3) There must be no feedback loops.

## Rules to construct A Causal Graph

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(1) There must be no hidden common causes.
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## Observations

- Even with these there is a lot of controversy as to its validity.


## Rules to construct A Causal Graph

## Conditions

(1) There must be no hidden common causes.
(2) There must not be selection bias.
(3) There must be no feedback loops.

## Observations

- Even with these there is a lot of controversy as to its validity.
- It seems to be false in quantum mechanical.


## Hidden Common Causes?

## Consider the following DAG



## Hidden Common Causes?

## Consider the following DAG



## Something Notable

- If a DAG is created on the basis of causal relationships between the variables under consideration,
- Then $X$ and $Y$ would be marginally independent according to the Markov condition.
- If Information is given to $H=h_{i}$


## Hidden Common Causes?

## Consider the following DAG



## Hidden Common Causes?

## Consider the following DAG



## However

- If $H$ is hidden, they will normally be dependent.


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## Inference in Bayesian Networks

What do we want from Bayesian Networks?
The main point of Bayesian Networkss is to enable probabilistic inference to be performed.

## Inference in Bayesian Networks

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## Two different types of inferences

(1) Belief Updating.

## Inference in Bayesian Networks

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The main point of Bayesian Networkss is to enable probabilistic inference to be performed.

## Two different types of inferences

(1) Belief Updating.
(2) Abduction Inference.

## Inference in Bayesian Networks

## Belief updating

It is used to obtain the posterior probability of one or more variables given evidence concerning the values of other variables.

## Inference in Bayesian Networks

## Belief updating

It is used to obtain the posterior probability of one or more variables given evidence concerning the values of other variables.

## Abductive inference

It finds the most probable configuration of a set of variables (hypothesis) given certain evidence.

## Using the Structure I

## Consider the following Bayesian Networks



## Using the Structure I

## Consider the following Bayesian Networks



## Consider answering a query in a Bayesian Network

- $Q=$ set of query variables


## Using the Structure I

## Consider the following Bayesian Networks



## Consider answering a query in a Bayesian Network

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- $e=$ evidence (set of instantiated variable-value pairs)


## Using the Structure I

## Consider the following Bayesian Networks



## Consider answering a query in a Bayesian Network

- $Q=$ set of query variables
- $e=$ evidence (set of instantiated variable-value pairs)
- Inference $=$ computation of conditional distribution $P(Q \mid e)$


## Using the Structure II

## Examples

- P(burglary|alarm)


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## So

Can we use the structure of the Bayesian Network to answer such queries efficiently?

## Using the Structure II

## Examples

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## So

Can we use the structure of the Bayesian Network to answer such queries efficiently?

## Answer YES

## Using the Structure II

## Examples

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## So

Can we use the structure of the Bayesian Network to answer such queries efficiently?

## Answer

## YES

- Note: Generally speaking, complexity is inversely proportional to sparsity of graph


## Outline

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## Example

## DAG



## Example

## DAG



We have the following model $p(a, b, c, d, e, f, g)$ is modeled by

$$
p(a, b, c, d, e, f, g)=p(a \mid b) p(c \mid b) p(f \mid e) p(g \mid e) p(b \mid d) p(e \mid d) p(d)
$$

## Example

## Given values in $C=c$ and $G=g$



## Example

Given values in $C=c$ and $G=g$


We want to calculate the following

$$
p(a \mid c, g)
$$

## Example

Then, if you have brute force approach


## Example

Then, if you have brute force approach


However, a direct calculation leads to use a demarginalization

$$
p(a \mid c, g)=\sum_{b, d, e, f} p(a, b, d, e, f \mid c, g)
$$

- This will require that if we fix the value of $a, c$ and $g$ to have a complexity of $O\left(m^{4}\right)$ with $m=\max \{|B|,|D|,|E|,|F|\}$


## Example

We get some information about $\left(a=a_{i}, c=c_{i}, g=g_{i}\right)$


## Thus, we have by the Markov Condition

## First, we use the chain representation

$$
p\left(a=a_{i}, b, d, e, f \mid c=c_{i}, g=g_{i}\right)=p\left(a=a_{i} \mid b, d, e, f, c=c_{i}, g=g_{i}\right) \times \cdots
$$

## Thus, we have by the Markov Condition

## First, we use the chain representation

$$
\begin{aligned}
p\left(a=a_{i}, b, d, e, f \mid c=c_{i}, g=g_{i}\right)= & p\left(a=a_{i} \mid b, d, e, f, c=c_{i}, g=g_{i}\right) \times \cdots \\
& \ldots p\left(b \mid d, e, f, c=c_{i}, g=g_{i}\right) \times \cdots
\end{aligned}
$$

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& \ldots p\left(b \mid d, e, f, c=c_{i}, g=g_{i}\right) \times \cdots \\
& \ldots p\left(d \mid e, f, c=c_{i}, g=g_{i}\right) \times \cdots
\end{aligned}
$$

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& \ldots p\left(b \mid d, e, f, c=c_{i}, g=g_{i}\right) \times \cdots \\
& \ldots p\left(d \mid e, f, c=c_{i}, g=g_{i}\right) \times \cdots \\
& \ldots\left(e \mid f, c=c_{i}, g=g_{i}\right) \times \cdots
\end{aligned}
$$

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p\left(a=a_{i}, b, d, e, f \mid c=c_{i}, g=g_{i}\right)= & p\left(a=a_{i} \mid b, d, e, f, c=c_{i}, g=g_{i}\right) \times \cdots \\
& \ldots p\left(b \mid d, e, f, c=c_{i}, g=g_{i}\right) \times \cdots \\
& \ldots p\left(d \mid e, f, c=c_{i}, g=g_{i}\right) \times \cdots \\
& \ldots\left(e \mid f, c=c_{i}, g=g_{i}\right) \times \cdots \\
& \ldots p\left(f \mid c=c_{i}, g=g_{i}\right) \times \cdots
\end{aligned}
$$

## Thus, we have by the Markov Condition

## First, we use the chain representation

$$
\begin{aligned}
p\left(a=a_{i}, b, d, e, f \mid c=c_{i}, g=g_{i}\right)= & p\left(a=a_{i} \mid b, d, e, f, c=c_{i}, g=g_{i}\right) \times \cdots \\
& \ldots p\left(b \mid d, e, f, c=c_{i}, g=g_{i}\right) \times \cdots \\
& \ldots p\left(d \mid e, f, c=c_{i}, g=g_{i}\right) \times \cdots \\
& \ldots\left(e \mid f, c=c_{i}, g=g_{i}\right) \times \cdots \\
& \ldots p\left(f \mid c=c_{i}, g=g_{i}\right) \times \cdots \\
& \ldots p\left(c=c_{i} \mid g=g_{i}\right) \times p\left(g=g_{i}\right)
\end{aligned}
$$

## Then, we have that

## Using the DAG structure

$$
\begin{aligned}
p\left(a=a_{i}, b, d, e, f \mid c=c_{i}, g=g_{i}\right)= & p\left(a=a_{i} \mid b\right) p\left(b \mid d, c=c_{i}\right) \times \cdots \\
& \ldots p(d \mid e) p\left(e, f \mid g=g_{i}\right)
\end{aligned}
$$

Then, we have that

## Using the DAG structure

$$
\begin{aligned}
p\left(a=a_{i}, b, d, e, f \mid c=c_{i}, g=g_{i}\right) & =p\left(a=a_{i} \mid b\right) p\left(b \mid d, c=c_{i}\right) \times \cdots \\
& \ldots p(d \mid e) p\left(e, f \mid g=g_{i}\right)
\end{aligned}
$$

Then given the original sum at the de-margenalization

$$
\begin{aligned}
p\left(a=a_{i}, b, d, e, f \mid c=c_{i}, g=g_{i}\right)= & \sum_{b} p\left(a=a_{i} \mid b\right) \sum_{d} p\left(b \mid d, c=c_{i}\right) \times \cdots \\
& \cdots \sum_{e} p(d \mid e) \sum_{f} p\left(e, f \mid g=g_{i}\right)
\end{aligned}
$$

Now, we can concentrate $\sum_{f} p\left(e, f \mid g=g_{i}\right)$
Now, using the relation with respect to $E$


Now, we can concentrate $\sum_{f} p\left(e, f \mid g=g_{i}\right)$
Now, using the relation with respect to $E$


Using this information, we can reduce one of the sums by marginalization

$$
\sum_{f} p\left(e, f \mid g=g_{i}\right)=p\left(e \mid g=g_{i}\right)
$$

## How?

## Remember that

$$
\sum_{f} p\left(e, f \mid g=g_{i}\right)=\sum_{f} p\left(e \mid f, g=g_{i}\right) p\left(f \mid g=g_{i}\right)
$$

## How?

## Remember that

$$
\begin{aligned}
\sum_{f} p\left(e, f \mid g=g_{i}\right) & =\sum_{f} p\left(e \mid f, g=g_{i}\right) p\left(f \mid g=g_{i}\right) \\
& =\sum_{f} p p\left(e \mid f, g=g_{i}\right)
\end{aligned}
$$

## Remember that

$$
\begin{aligned}
\sum_{f} p\left(e, f \mid g=g_{i}\right) & =\sum_{f} p\left(e \mid f, g=g_{i}\right) p\left(f \mid g=g_{i}\right) \\
& =\sum_{f} p p\left(e \mid f, g=g_{i}\right) \\
& =p\left(e \mid g=g_{i}\right)
\end{aligned}
$$

Then, we have that

## DAG



Then, we have that

## DAG



Thus, we can reduce the size of our sum

$$
\sum_{b} p\left(a=a_{i} \mid b\right) \sum_{d} p\left(b \mid d, c=c_{i}\right) \sum_{e} p(d \mid e) p\left(e \mid g=g_{i}\right)
$$

Then, we can use the realtion with respect to $D$

## Given the following DAG



Then, we can use the realtion with respect to $D$

## Given the following DAG



Now, we can calculate the probability of $D$ by using the chain rule

$$
p(d \mid e) p\left(e \mid g=g_{i}\right)=p\left(d \mid e, g=g_{i}\right) p\left(e \mid g=g_{i}\right)=p\left(d, e \mid g=g_{i}\right)
$$

## Example

## DAG



## Example

## DAG



Now, we can calculate the probability of $D$ by using the chain rule

$$
\sum_{b} p\left(a=a_{i} \mid b\right) \sum_{d} p\left(b \mid d, c=c_{i}\right) \sum_{e} p\left(d, e \mid g=g_{i}\right)
$$

## Example

## DAG



## Example

## DAG



Now, we sum over all possible values of $E$

$$
\sum_{e} p\left(d, e \mid g=g_{i}\right)=p\left(d \mid g=g_{i}\right)
$$

## Example

## DAG



## Example

## DAG



We get the following

$$
\sum_{b} p\left(a=a_{i} \mid b\right) \sum_{d} p\left(b \mid d, c=c_{i}\right) p\left(d \mid g=g_{i}\right)
$$

## Example

## DAG



## Example

## DAG



Again the chain rule for $D$

$$
\begin{aligned}
p\left(b \mid d, c=c_{i}\right) p\left(d \mid g=g_{i}\right) & =p\left(b \mid d, c=c_{i}, g=g_{i}\right) p\left(d \mid c=c_{i}, g=g_{i}\right) \\
& =p\left(b, d \mid c=c_{i}, g=g_{i}\right)
\end{aligned}
$$

## Example

## DAG



## Example

## DAG



Now, we sum over all possible values of $D$

$$
\sum_{b} p\left(a=a_{i} \mid b\right) p\left(b \mid c=c_{i}, g=g_{i}\right)
$$

## Example

## DAG



## Example

## DAG



Now, we use the chain rule for reducing again

$$
p\left(a=a_{i} \mid b\right) p\left(b \mid c=c_{i}, g=g_{i}\right)=p\left(a=a_{i}, b \mid c=c_{i}, g=g_{i}\right)
$$

## Example

## DAG



## Example

## DAG



Now, we use the chain rule for reducing again

$$
\sum_{b} p\left(a=a_{i}, b \mid c=c_{i}, g=g_{i}\right)=p\left(a=a_{i} \mid c=c_{i}, g=g_{i}\right)
$$

## Complexity

Because this can be computed using a sequence of four for loops The complexity simply becomes $O(m)$ when compared with $O\left(m^{4}\right)$

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## General Strategy for Inference

## Query

- Want to compute $P(q \mid e)!!!$


## General Strategy for Inference

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## Step 1

- $P(q \mid e)=\frac{P(q, e)}{P(e)}=a P(q, e)$, since $a=P(e)$ is constant wrt $Q$.


## General Strategy for Inference

## Query

- Want to compute $P(q \mid e)!!!$


## Step 1

- $P(q \mid e)=\frac{P(q, e)}{P(e)}=a P(q, e)$, since $a=P(e)$ is constant wrt $Q$.


## Step 2

- $P(q, e)=\sum_{a . . z} P(q, e, a, b, \ldots . z)$, by the law of total probability.


## General Strategy for inference

Step 3

- $\sum_{a . . z} P(q, e, a, b, \ldots . z)=\sum_{a . . z} \Pi P($ variable $i \mid$ parents $i$ ) (using Bayesian network factoring)


## General Strategy for inference

Step 3

- $\sum_{a . . z} P(q, e, a, b, \ldots . z)=\sum_{a . z} \Pi P($ variable $i \mid$ parents $i$ ) (using Bayesian network factoring)


## Step 4

- Distribute summations across product terms for efficient computation.


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## Inference - An Overview

## Case 1

- Trees and singly connected networks - only one path between any two nodes:


## Inference - An Overview

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## Case 2

- Multiply connected networks:


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- Trees and singly connected networks - only one path between any two nodes:
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## Case 2

- Multiply connected networks:
- A range of algorithms including cut-set conditioning (Pearl, 1988), junction tree propagation (Lauritzen and Spiegelhalter, 1988), bucket elimination (Dechter, 1996) to mention a few.


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## Notes

- Both exact and approximate inference are NP-hard in the worst case.


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- Multiply connected networks:
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- A range of algorithms for approximate inference.


## Notes

- Both exact and approximate inference are NP-hard in the worst case.
- Here the focus will be on message passing and junction tree propagation for discrete variables.

