Introduction to Artificial Intelligence Introduction to Bayesian Networks

Andres Mendez-Vazquez

February 11, 2020

Outline

Introduction

The History of Bayesian Applications

Bayes Theorem

- Everything Starts at Someplace
- Why Bayesian Networks?

2 Bayesian Networks

- Definition
- Markov Condition
 - Example
- Using the Markov Condition
- Representing the Joint Distribution
 - Example
 - Observations
- Markov Condition and DAG's
 - Example
- Causality and Bayesian Networks
 - Precautionary Tale
- Causal DAG
- The Causal Markov Condition
- Inference in Bayesian Networks
- Example
- General Strategy of Inference
- Inference An Overview



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- 1968 Attempts to use probabilities in expert systems (Gorry & Barnett).
- 1973 Gave up to heavy calculations! (Gorry).
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Summary until mid '80s

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- 1995 In Windows95[™] for printer-trouble shooting and Office assistance ("the paper clip").
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Furtheron 2000-2015

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- Spam Detection.
- Gene Discovery.
- Signal Processing.
- Ranking.
- Forecasting.
- etc.

Something Notable

We are interested more and more on building automatically Bayesian Networks using data!!!



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Many of Them

- Since in a Bayesian network encodes all variables, missing data entries can be handled successfully.
- When used for learning casual relationships, they help better understand a problem domain as well as forecast consequences
- it is ideal to use a Bayesian network for representing prior data and knowledge.
- Over-fitting of data can be avoidable when using Bayesian networks and Bayesian statistical methods.



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One Version

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- P(A) is the **prior probability** or marginal probability of A. It is "prior" in the sense that it does not take into account any information about B.
- P(A|B) is the conditional probability of A, given B. It is also called the posterior probability because it is derived from or depends upon the specified value of B.
- P(B|A) is the conditional probability of B given A. It is also called the likelihood.
- *P*(*B*) is the **prior or marginal probability** of B, and acts as a normalizing constant.

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What is the probability that a person has taken the drug?

$$P\left(D = y | T = +ve\right) = \frac{P\left(T = +ve | D = y\right) P\left(D = y\right)}{P\left(T = +ve | D = y\right) P\left(D = y\right) + P\left(T = +ve | D = n\right) P\left(D = n\right)}$$

Let me develop the equation

Using simply

P(A,B) = P(A|B) P(B) (Chain Rule)



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Increase Complexity

- Suppose now that there is a similar link between Lung Cancer (L) and a chest X-ray (X) and that we also have the following relationships:
 - History of smoking (S) has a direct influence on bronchitis (B) and lung cancer (L);
 - L and B have a direct influence on fatigue (F)



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Question

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Short Hand

$$P(b_1|s_1, f_1, x_1) = \frac{P(b_1, s_1, f_1, x_1)}{P(s_1, f_1, x_1)} = \frac{\sum_l P(b_1, s_1, f_1, x_1, l)}{\sum_{b,l} P(b, s_1, f_1, x_1, l)}$$

Values for the Complex Case

Table

Feature	Value	When the Feature Takes this Value
Н	h_1	There is a history of smoking
	h_2	There is no history of smoking
В	b_1	Bronchitis is present
	b_2	Bronchitis is absent
L	l_1	Lung cancer is present
	l_2	Lung cancer is absent
F	f_1	Fatigue is present
	f_2	Fatigue is absent
С	c_1	Chest X-ray is positive
	c_2	Chest X-ray is negative



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The joint probability distribution P(H, B, L, F, C)

• For five binary variables there are $2^5 = 32$ values in the joint distribution (for 100 variables there are over 2^{100} values)

• How are these values to be obtained



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Ok!!!

• We need something BETTER!!!



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Definition

A Bayesian network consists of

- A Graph
 - Nodes represent the random variables.
 - Directed edges (arrows) between pairs of nodes
 - it must be a Directed Acyclic Graph (DAG) no directed cycles
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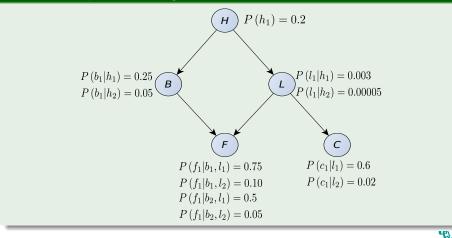
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Example

DAG for the previous Lung Cancer Problem



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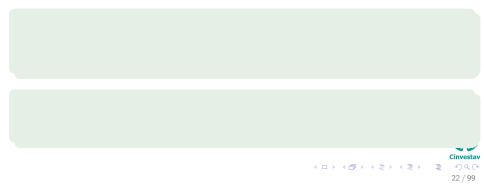


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• Suppose we have a joint probability distribution P of the random variables in some set V and a DAG G = (V, E).

We say that (G, P) satisfies the Markov condition if for each variable X ∈ V, {X} is conditionally independent of the set of all its non-descendents given the set of all its parents.



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Notation

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We use the following the notation

 $I_P\left(\left\{X\right\}, ND_X | PA_X\right)$

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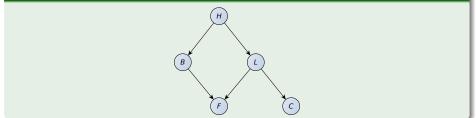
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Example

We have that



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Example

We have that

B

Given the previous DAG we have

Node	PA	Conditional Independence
C	$\{L\}$	$I_P(\{C\},\{H,B,F\} \{L\})$
B	$\{H\}$	$I_{P}(\{B\},\{L,C\} \{H\})$
F	$\{B,L\}$	$I_{P}(\{F\},\{H,C\} \{B,L\})$
L	$\{H\}$	$I_{P}(\{L\},\{B\} \{H\})$

L

c

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First Decompose a Joint Distribution using the Chain Rule

P(c, f, l, b, h) = P(c|b, s, l, f) P(f|b, h, l) P(l|b, h) P(b|h) P(h)(2)

Using the Markov condition in the following DAG

We have the following equivalences

•
$$P(c|b,h,l,f) = P(c|l)$$

•
$$P(f|b,h,l) = P(f|b,l)$$

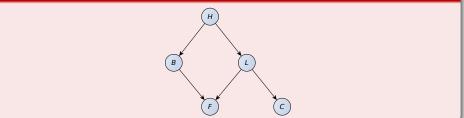
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$$P(l|b,h) = P(l|h)$$



First Decompose a Joint Distribution using the Chain Rule

P(c, f, l, b, h) = P(c|b, s, l, f) P(f|b, h, l) P(l|b, h) P(b|h) P(h)(2)

Using the Markov condition in the following DAG



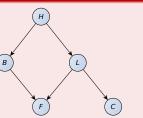
We have the following equivalences

- P(c|b,h,l,f) = P(c|l)
- $P\left(f|b,h,l\right) = P\left(f|b,l\right)$
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 ight)=P\left(c|l
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- $P\left(f|b,h,l\right) = P\left(f|b,l\right)$

•
$$P(l|b,h) = P(l|h)$$

Finally

$$P(c, f, l, b, h) = P(c|l) P(f|b, l) P(l|h) P(b|h) P(h)$$

(3)

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Representing the Joint Distribution

Theorem (Product of Conditional Probabilities of the Parents)

If (G, P) satisfies the Markov condition, then P is equal to the product of its conditional distributions of all nodes given values of their parents, whenever these conditional distributions exist.

General Representation

• In general, for a network with nodes $X_1, X_2, ..., X_n \Rightarrow$

$$P(x_1, x_2, ..., x_n) = \prod_{i=1}^{n} P(x_i | PA(x_i))$$



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We prove the case where \boldsymbol{P} is discrete

Order the nodes so that if \boldsymbol{Y} is a descendant of $\boldsymbol{Z},$ then \boldsymbol{Y} follows \boldsymbol{Z} in the ordering.

Topological Sorting.



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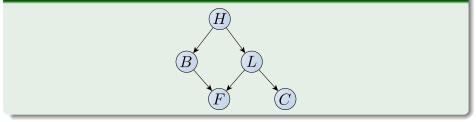
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For example

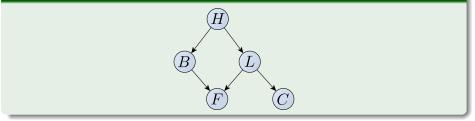


The ancestral ordering are

 $\left[H,L,B,C,F
ight]$ and $\left[H,B,L,F,C
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For example



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(4)



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Now

Let $X_1, X_2, ..., X_n$ be the resultant ordering.

For a given set of values of $x_1, x_2, ..., x_n$

Let pa_i be the subsets of these values containing the values of $X_i's$ parents

Thus, we need to prove that whenever $P\left(\mathsf{pa}_{i} ight) eq 0$ for $1\leq i\leq n$

 $P\left(x_{n}, x_{n-1}, \dots, x_{1}\right) = P\left(x_{n} | \mathsf{pa}_{n}\right) P\left(x_{n-1} | \mathsf{pa}_{n-1}\right) \dots P\left(x_{1} | \mathsf{pa}_{1}\right) \qquad (5)$



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Something Notable

We show this using induction on the number of variables in the network.

Assume then $P\left(\mathrm{pa}_{i}\right)\neq0$ for $1\leq i\leq n$ for a combination of x_{i}' values.



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Since pa_1 is empty, then

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(6)

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(7)

Inductive Step

We need show for this combination of values of the x_i 's that

$$P(x_{i+1}, x_i, ..., x_1) = P(x_{i+1} | \mathsf{pa}_{i+1}) P(x_i | \mathsf{pa}_i) ... P(x_1 | \mathsf{pa}_1)$$
(8)

Case

For this combination of values:

$$P(x_i, x_{i-1}, ..., x_1) = 0$$

By Conditional Probability, we have

 $P(x_{i+1}, x_i, ..., x_1) = P(x_{i+1} | x_i, ..., x_1) P(x_i, ..., x_1) = 0$ (10)



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 (10)

Due to the previous equalities and the inductive hypothesis

There is some k, $1 \le k \le i$ such that $P(x_k | \mathsf{pa}_k) = 0$ because after all

$$P(x_i|pa_i) P(x_{i-1}|pa_{i-1}) \dots P(x_1|pa_1) = 0$$
(11)

Thus, the equality holds

Now for the Case 2

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For this combination of values $P\left(x_{i}, x_{i-1}, ..., x_{1}
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Case 2

For this combination of values $P(x_i, x_{i-1}, ..., x_1) \neq 0$



Thus by the Rule of Conditional Probability

$$P(x_{i+1}, x_i, ..., x_1) = P(x_{i+1}|x_i, ..., x_1) P(x_i, ..., x_1)$$



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Definition Markov Condition (Remember!!!)

• Suppose we have a joint probability distribution P of the random variables in some set V and a DAG G = (V, E).



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Definition Markov Condition (Remember!!!)

- Suppose we have a joint probability distribution P of the random variables in some set V and a DAG G = (V, E).
 - We say that (G, P) satisfies the Markov condition if for each variable X ∈ V, {X} is conditionally independent of the set of all its non-descendents given the set of all its parents.



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Given this Markov Condition and the fact that $X_1,...,X_i$ are all non-descendants of X_{i+1}

We have that

$$P(x_{i+1}, x_i, ..., x_1) = P(x_{i+1} | \mathsf{pa}_{i+1}) P(x_i, ..., x_1)$$



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= $P(x_{i+1} | \mathsf{pa}_{i+1}) P(x_i | \mathsf{pa}_i) \cdots P(x_1 | \mathsf{pa}_1)$ (IH)

Q.E.D.



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Example

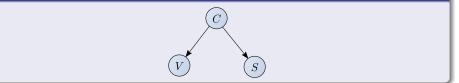
Imagine the following Random Variables

Variable	Value	Outcome	
V	v_1	All objects containing a '1'	
	v_2	All objects containing a '2'	
S	s_1	All square objects	
	s_2	All round objects	
C	c_1	All black objects	
	c_2	All white objects	



Example

Using the following graph



Using the chain rule

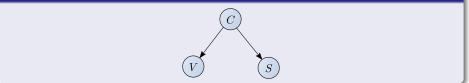
$$\begin{split} P\left(v,s,c\right) &= P\left(v|s,c\right) P\left(s|c\right) P\left(c\right) \\ &= P\left(v|c\right) P\left(s|c\right) P\left(c\right) \end{split}$$



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Example

Using the following graph



Using the chain rule

$$P(v, s, c) = P(v|s, c) P(s|c) P(c)$$
$$= P(v|c) P(s|c) P(c)$$



Then, using the following probabilities

c	s	v	$P\left(v s,c ight)$	$P\left(v c\right)$
c_1	s_1	v_1	1/3	1/3
c_1	s_1	v_2	2/3	2/3
c_1	s_2	v_1	1/3	1/3
c_1	s_2	v_2	2/3	2/3
c_2	s_1	v_1	1/2	1/2
c_2	s_1	v_2	1/2	1/2
c_2	s_2	v_1	1/2	1/2
c_2	s_2	v_2	1/2	1/2

Therefore

We have the following probabilities

$$P(c_1, s_1, v_1) = \frac{2}{13}$$

With the following using the Markov Conditio

$P(v_1|c_1) P(s_1|c_1) P(c_1) = P(One|Black) P(Square|Black) P(Black)$ $= \frac{1}{3} \times \frac{2}{3} \times \frac{9}{13} = \frac{2}{13}$



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OBSERVATIONS

• There are good savings in the Number of Values

Brute Force Approach

• on n binary variables requires m^n , if $m = \max \{|v_i| | V\}_{i=1}^n$.

For a Bayesian Network with n binary variables and each node has attended most k parents

• Then, less than $m^k n$ values are required!!!



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Theorem (Markov Condition on a DAG)

- Let a DAG G be given in which each node is a random variable, and let a discrete conditional probability distribution of each node given values of its parents in G be specified.
- Then, the product of these conditional distributions yields a joint probability distribution P of the variables, and (G, P) satisfies the Markov condition.



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Often in the case of continuous distributions it still holds.



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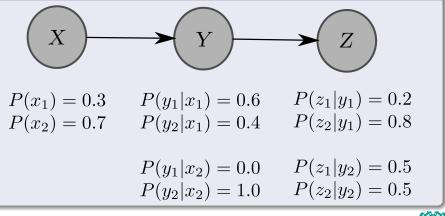
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Example

We have the following DAG and probabilities





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We have the according to a Markov Condition on a DAG

$P\left(x,y,z\right) = P\left(z|y\right)P\left(y|x\right)P\left(x\right)$

Which, we have that

• It satisfies the Markov Condition.



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Definition of a Cause

The one, such as a person, an event, or a condition, that is responsible for an action or a result.



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However

• Although useful, this simple definition is certainly not the last word on the concept of causation.

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Definition of a Cause

The one, such as a person, an event, or a condition, that is responsible for an action or a result.

However

- Although useful, this simple definition is certainly not the last word on the concept of causation.
 - Actually Philosophers are still wrangling the issue!!!



Nevertheless, It sheds light in the issue

• If the action of making variable X take some value sometimes changes the value taken by a variable Y.

$$(X) \xrightarrow{\text{Causality}} Y$$

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• If the action of making variable X take some value sometimes changes the value taken by a variable Y.

$$(X) \xrightarrow{\text{Causality}} Y$$

Here, we assume \boldsymbol{X} is responsible for sometimes changing \boldsymbol{Y} 's value

• Thus, we conclude X is a cause of Y.



Formally

We say we **manipulate** X when we force X to take some value.

• We say X causes Y if there is some manipulation of X that leads to a change in the probability distribution of Y.



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Important

Not every Bayesian Networks describes causal relationships between the variables.



Important

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• Consider the dependence between Lung Cancer, L, and the X-ray test, X.

By focusing on just these variables we might be tempted to represent them by the following Bayesian Networks.



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$$P(l_1) = 0.001$$

 $P(x_1|l_1) = 0.6$
 $P(x_1|l_2) = 0.02$



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Remark

Be Careful

• It is tempting to think that Bayesian Networks can be created by creating a DAG where the edges represent direct causal relationships between the variables.



Outline

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Causal DAG

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Causal DAG

• Given a set of variables V, if for every $X, Y \in V$ we draw an edge from X to $Y \iff X$ is a direct cause of Y relative to V, we call the resultant DAG a **causal DAG**.



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In General

• The Markov condition holds for a causal DAG.



However, we still want to know if the Markov Condition Holds

Remark

There are several thing that the DAG needs to have in order to have the Markov Condition.



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Examples of those

Common Causes



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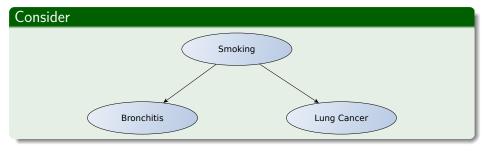
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Examples of those

- Common Causes
- Common Effects



How to have a Markov Assumption : Common Causes



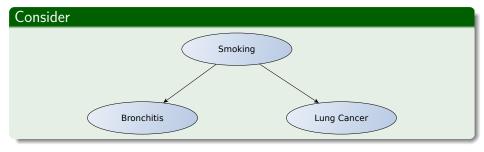
Markov condition

$I_p(\{B\}, \{L\} | \{S\}) \Rightarrow P(B|L, S) = P(B|S)$



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How to have a Markov Assumption : Common Causes



Markov condition

$$I_p(\{B\}, \{L\} | \{S\}) \Rightarrow P(B|L, S) = P(B|S)$$
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If we know the causal relationships

$S \to B$ and $S \to L$

(13)

Now!!!

If we know that you smoke...



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Then, because of the blocking of information from smoking

• Finding out that Bronchitis will not give us any more information about the probability of having Lung Cancer.



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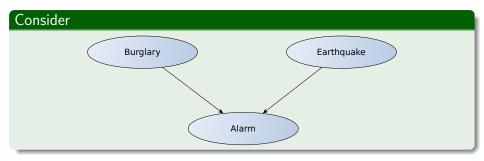
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Markov condition

It is satisfied!!!



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Markov Condition

 $l_p(B, W) \Rightarrow P(B|E) = P(B)$

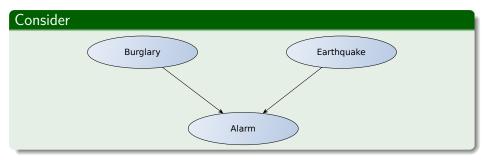
(14)

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Thus

We would expect Raining and Ballgame to be independent of each other which is in agreement with the Markov condition.



Markov Condition

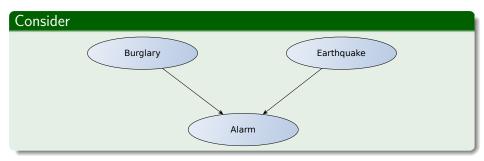
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However

We would, however expect them to be conditionally dependent given Alarm.

Thus

If the alarm has gone off, news that there had been an earthquake would 'explain away' the idea that a burglary had taken place.

Then

Again in agreement with the Markov condition.



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The Causal Markov Condition

What do we want?

The basic idea is that the Markov condition holds for a causal DAG.



Conditions

- There must be no hidden common causes.
 - There must not be selection bias.
 - There must be no feedback loops.



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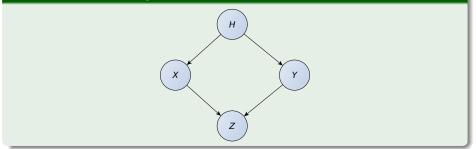
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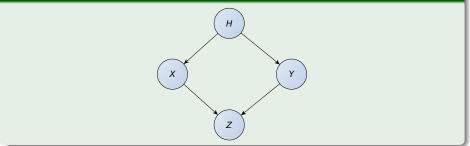
Consider the following DAG



Something Notable

- If a DAG is created on the basis of causal relationships between the variables under consideration,
 - Then X and Y would be marginally independent according to the Markov condition.
 - If Information is given to $H = h_i$

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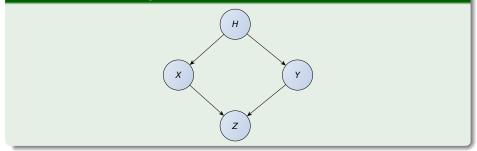


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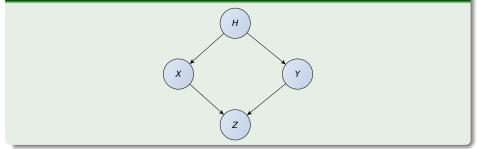


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• If H is hidden, they will normally be dependent.



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What do we want from Bayesian Networks?

The main point of Bayesian Networkss is to enable probabilistic inference to be performed.



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Two different types of inferences

- Belief Updating.
- Ø Abduction Inference.



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Belief updating

It is used to obtain the posterior probability of one or more variables given evidence concerning the values of other variables.

Abductive inference

It finds the most probable configuration of a set of variables (hypothesis) given certain evidence.



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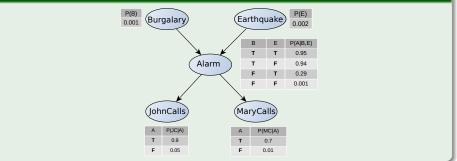
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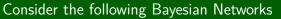


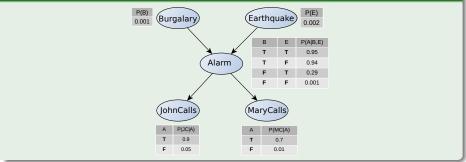
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Consider the following Bayesian Networks









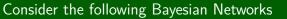
 Consider answering a query in a Bayesian Network

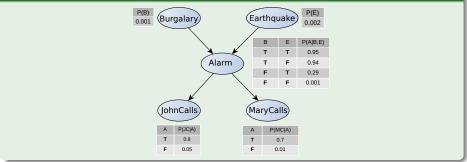
 • Q= set of query variables

 • computation of conditional distribution Project

 • interence --- computation of conditional distribution Project

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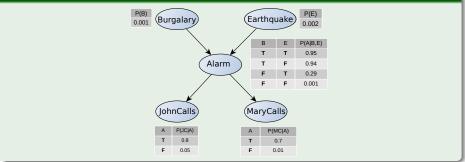
Consider answering a query in a Bayesian Network

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Inference = computation of conditional distribution P(Q)

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Consider answering a query in a Bayesian Network

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Examples

- P(burglary|alarm)
 - P(earthquake | JCalls, MCalls)
- $\bullet P(JCalls, MCalls | burglary, earthquake)$

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YES

 Note: Generally speaking, complexity is inversely proportional to sparsity of graph

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Using the Structure II

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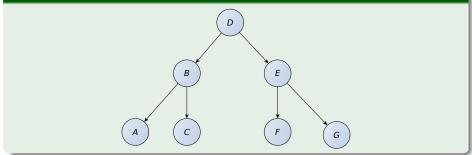
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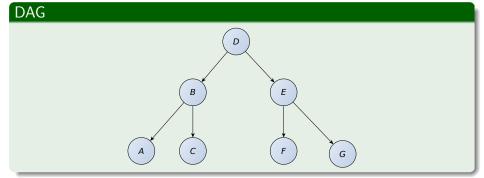
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 $p\left(a,b,c,d,e,f,g
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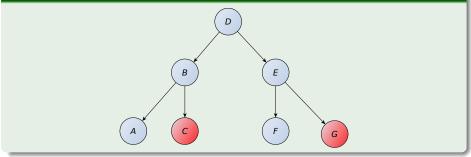
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Given values in C = c and G = g

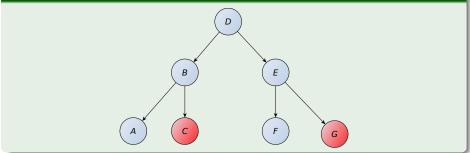


We want to calculate the following

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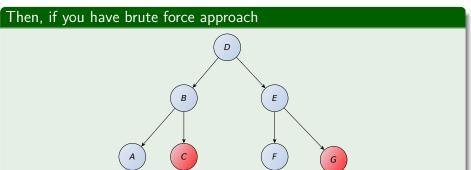
$$p\left(a|c,g\right)$$

Then, if you have brute force approach

However, a direct calculation leads to use a demarginalization

$$p\left(a|c,g\right) = \sum_{b,d,e,f} p\left(a,b,d,e,f|c,g\right)$$

• This will require that if we fix the value of a, c and g to have a complexity of $O(m^4)$ with $m = \max\{|B|, |D|, |E|, |F|\}$

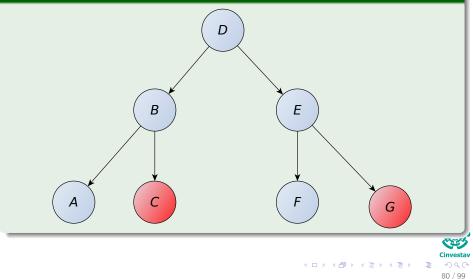


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We get some information about $(a = a_i, c = c_i, g = g_i)$



First, we use the chain representation

$$p(a = a_i, b, d, e, f | c = c_i, g = g_i) = p(a = a_i | b, d, e, f, c = c_i, g = g_i) \times \cdots$$

$$\dots p\left(d|e_{i}f_{i}c = c_{i}, g = g_{i}\right) \times \dots$$

$$\dots \left(c|f_{i}c = c_{i}, g = g_{i}\right) \times \dots$$

$$\dots p\left(f|c = c_{i}, g = g_{i}\right) \times \dots$$

$$\dots p\left(c = c_{i}|g = g_{i}\right) \times p\left(g = g_{i}\right)$$

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First, we use the chain representation

$$p(a = a_i, b, d, e, f | c = c_i, g = g_i) = p(a = a_i | b, d, e, f, c = c_i, g = g_i) \times \cdots$$
$$\dots p(b | d, e, f, c = c_i, g = g_i) \times \cdots$$
$$\dots p(d | e, f, c = c_i, g = g_i) \times \cdots$$
$$\dots (e | f, c = c_i, g = g_i) \times \cdots$$
$$\dots p(f | c = c_i, g = g_i) \times \cdots$$



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$$\dots p(f | c = c_i, g = g_i) \times \cdots$$

$$\dots p(c = c_i | g = g_i) \times p(g = g_i)$$



Then, we have that

Using the DAG structure

$$p(a = a_i, b, d, e, f | c = c_i, g = g_i) = p(a = a_i | b) p(b | d, c = c_i) \times \cdots$$
$$\dots p(d | e) p(e, f | g = g_i)$$

I hen given the original sum at the de-margenalization

$$p(a = a_i, b, d, e, f | c = c_i, g = g_i) = \sum_b p(a = a_i | b) \sum_d p(b | d, c = c_i) \times \cdots$$
$$\dots \sum_e p(d | e) \sum_f p(e, f | g = g_i)$$



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Using the DAG structure

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...p(d|e) p(e, f | g = g_i)

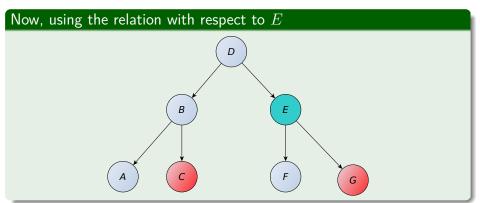
Then given the original sum at the de-margenalization

$$p(a = a_i, b, d, e, f | c = c_i, g = g_i) = \sum_b p(a = a_i | b) \sum_d p(b | d, c = c_i) \times \cdots$$
$$\dots \sum_e p(d | e) \sum_f p(e, f | g = g_i)$$



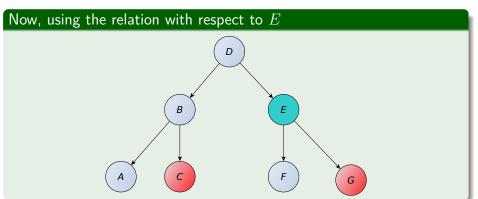
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Now, we can concentrate $\sum_{f} p(e, f | g = g_i)$



Using this information, we can reduce one of the sums by marginalization

Now, we can concentrate $\sum_{f} p(e, f | g = g_i)$



Using this information, we can reduce one of the sums by marginalization

$$\sum_{f} p\left(e, f | g = g_i\right) = p\left(e | g = g_i\right)$$

How?

Remember that

$$\sum_{f} p(e, f | g = g_i) = \sum_{f} p(e | f, g = g_i) p(f | g = g_i)$$



How?

Remember that

$$\sum_{f} p(e, f|g = g_i) = \sum_{f} p(e|f, g = g_i) p(f|g = g_i)$$
$$= \sum_{f} pp(e|f, g = g_i)$$



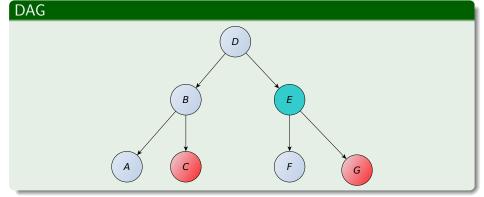
How?

Remember that

$$\sum_{f} p(e, f|g = g_i) = \sum_{f} p(e|f, g = g_i) p(f|g = g_i)$$
$$= \sum_{f} pp(e|f, g = g_i)$$
$$= p(e|g = g_i)$$



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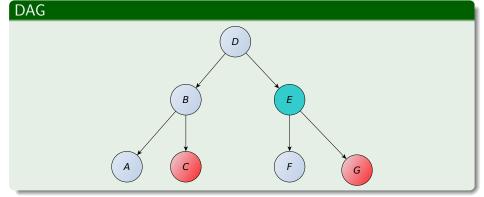


hus, we can reduce the size of our sum

 $\sum_{b} p\left(a = a_{i}|b\right) \sum_{d} p\left(b|d, c = c_{i}\right) \sum_{e} p\left(d|e\right) p\left(e|g = g_{i}\right)$

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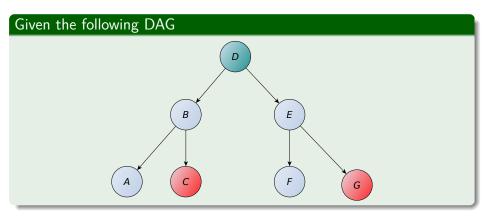


Thus, we can reduce the size of our sum

$$\sum_{b} p\left(a = a_{i}|b\right) \sum_{d} p\left(b|d, c = c_{i}\right) \sum_{e} p\left(d|e\right) p\left(e|g = g_{i}\right)$$

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Then, we can use the realtion with respect to \boldsymbol{D}



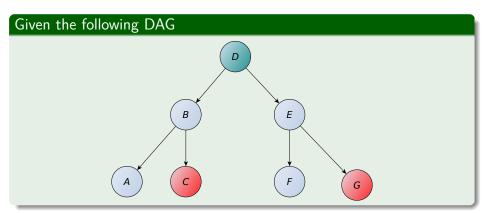
Now, we can calculate the probability of D by using the chain rule

 $p(d|e) p(e|g = g_i) = p(d|e, g = g_i) p(e|g = g_i) = p(d, e|g = g_i)$

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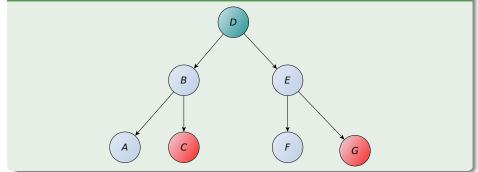
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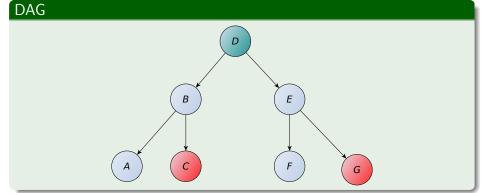
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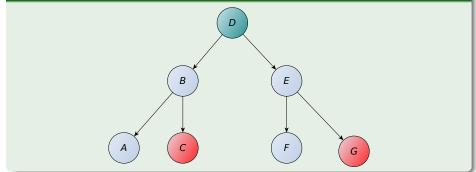
Now, we can calculate the probability of D by using the chain rule

$$\sum_{b} p\left(a = a_i | b\right) \sum_{d} p\left(b | d, c = c_i\right) \sum_{e} p\left(d, e | g = g_i\right)$$

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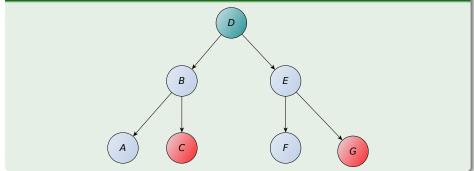


Now, we sum over all possible values of J

 $\sum p(d, e|g = g_i) = p(d|g = g_i)$

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Now, we sum over all possible values of E

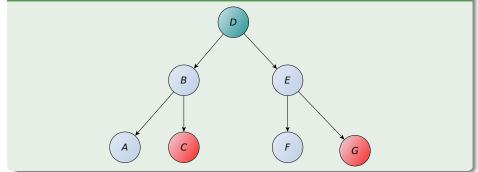
$$\sum_{e} p\left(d, e | g = g_i\right) = p\left(d | g = g_i\right)$$

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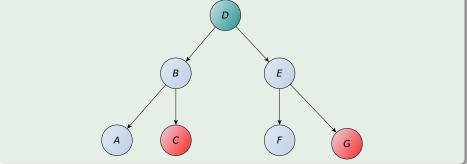


We get the following

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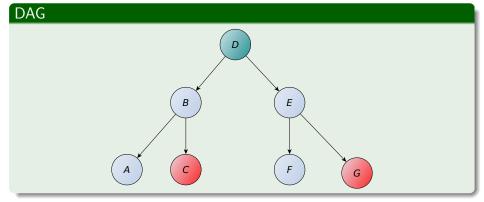




We get the following

$$\sum_{b} p\left(a = a_i | b\right) \sum_{d} p\left(b | d, c = c_i\right) p\left(d | g = g_i\right)$$

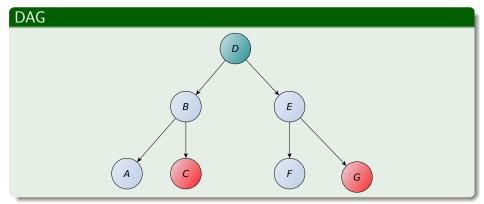
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Again the chain rule for L

$p(b|d, c = c_i) p(d|g = g_i) = p(b|d, c = c_i, g = g_i) p(d|c = c_i, g = g_i)$ $= p(b, d|c = c_i, g = g_i)$

S LP P

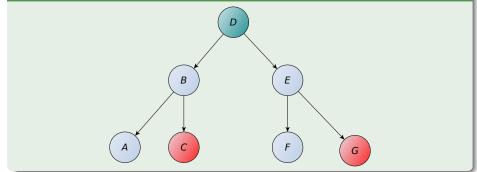


Again the chain rule for D

$$p(b|d, c = c_i) p(d|g = g_i) = p(b|d, c = c_i, g = g_i) p(d|c = c_i, g = g_i)$$
$$= p(b, d|c = c_i, g = g_i)$$







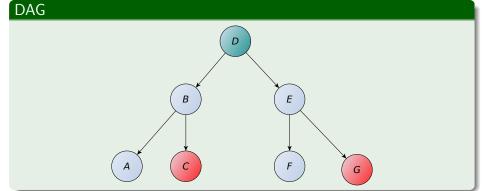
Now, we sum over all possible values of 1

$$\sum_{b} p\left(a = a_i | b\right) p\left(b | c = c_i, g = g_i\right)$$

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Now, we sum over all possible values of D

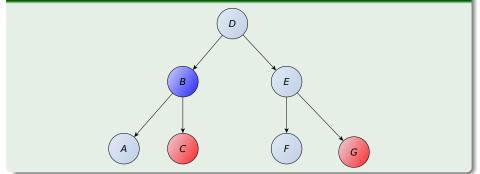
$$\sum_{b} p\left(a = a_i | b\right) p\left(b | c = c_i, g = g_i\right)$$

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Example

DAG



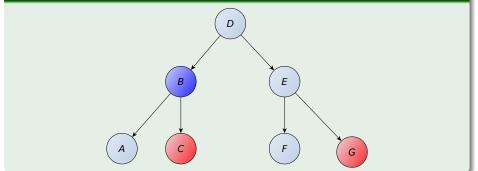
Now, we use the chain rule for reducing again

 $p(a = a_i|b) p(b|c = c_i, g = g_i) = p(a = a_i, b|c = c_i, g = g_i)$

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Example

DAG



Now, we use the chain rule for reducing again

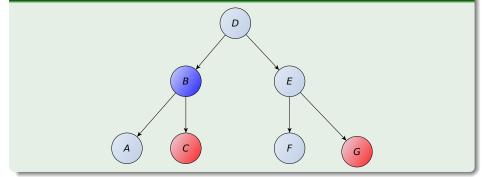
$$p(a = a_i|b) p(b|c = c_i, g = g_i) = p(a = a_i, b|c = c_i, g = g_i)$$

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DAG



Now, we use the chain rule for reducing again

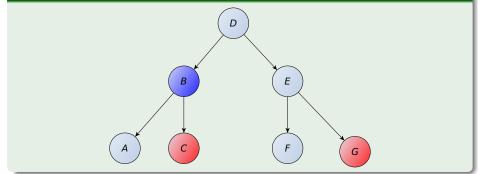
 $\sum_{b} p(a = a_i, b | c = c_i, g = g_i) = p(a = a_i | c = c_i, g = g_i)$

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Now, we use the chain rule for reducing again

$$\sum_{b} p(a = a_i, b | c = c_i, g = g_i) = p(a = a_i | c = c_i, g = g_i)$$

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Complexity

Because this can be computed using a sequence of four for loops

The complexity simply becomes $O\left(m
ight)$ when compared with $O\left(m^4
ight)$



Outline

Introduction

The History of Bayesian Applications

Bayes Theorem

- Everything Starts at Someplace
- Why Bayesian Networks?

2 Bayesian Networks

- Definition
- Markov Condition

Example

- Using the Markov Condition
- Representing the Joint Distribution
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- The Causal Markov Condition
- Inference in Bayesian Networks
- Example

General Strategy of Inference

Inference - An Overview



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General Strategy for Inference

Query

• Want to compute P(q|e)!!!

Step 1

• $P(q|e) = \frac{P(q,e)}{P(e)} = aP(q,e)$, since a = P(e) is constant wrt Q.

Step 2

• $P(q,e) = \sum_{a..z} P(q,e,a,b,\ldots,z)$, by the law of total probability.



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General Strategy for inference

Step 3

• $\sum_{a..z} P(q, e, a, b, ..., z) = \sum_{a..z} \prod P(\text{variable } i \mid \text{parents } i)$ (using Bayesian network factoring)

Distribute summations across product terms for efficient computation.



General Strategy for inference

Step 3

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$$\sum_{a..z} P(q, e, a, b, ..., z) = \sum_{a..z} \prod P(\text{variable } i \mid \text{parents } i)$$
 (using Bayesian network factoring)

Step 4

• Distribute summations across product terms for efficient computation.



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Case 1

- Trees and singly connected networks only one path between any two nodes:
 - ▶ Message passing (Pearl, 1988)

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 - Message passing (Pearl, 1988)

• Multiply connected networks:

- A range of algorithms including cut-set conditioning (Pearl, 1988), junction tree propagation (Lauritzen and Spiegelhalter, 1988), bucket elimination (Dechter, 1996) to mention a few.
- A range of algorithms for approximate inference.

Case 1

- Trees and singly connected networks only one path between any two nodes:
 - Message passing (Pearl, 1988)

Case 2

• Multiply connected networks:

A range of algorithms including cut-set conditioning (Pearl, 1988), junction tree propagation (Lauritzen and Spiegelhalter, 1988), bucket elimination (Dechter, 1996) to mention a few.

A range of algorithms for approximate inference.

Both exact and approximate inference are NP-hard in the worst case

 Here the focus will be on message passing and junction tree propagation for discrete variables.

Case 1

- Trees and singly connected networks only one path between any two nodes:
 - Message passing (Pearl, 1988)

Case 2

- Multiply connected networks:
 - A range of algorithms including cut-set conditioning (Pearl, 1988), junction tree propagation (Lauritzen and Spiegelhalter, 1988), bucket elimination (Dechter, 1996) to mention a few.

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 Here the focus will be on message passing and junction tree propagation for discrete variables.

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- Trees and singly connected networks only one path between any two nodes:
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